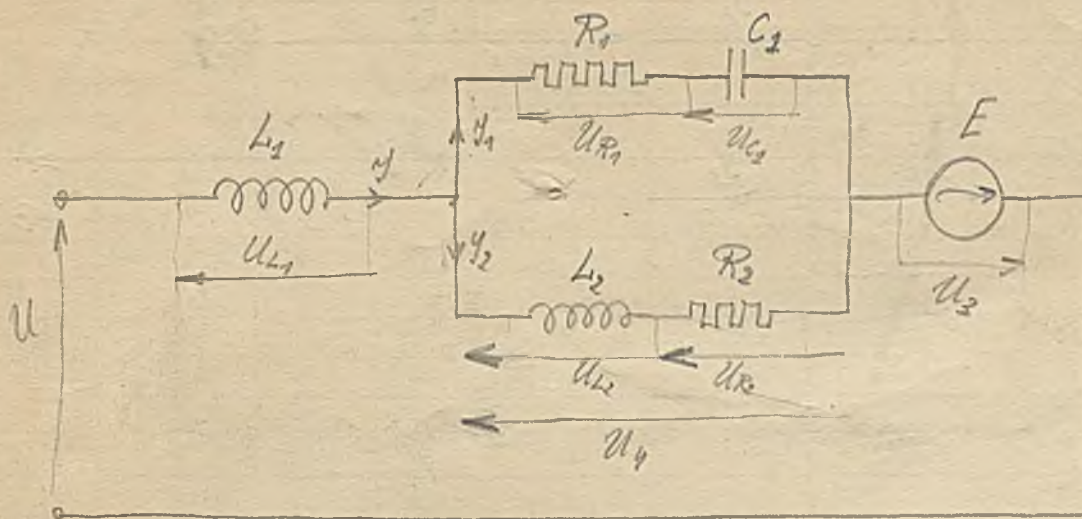
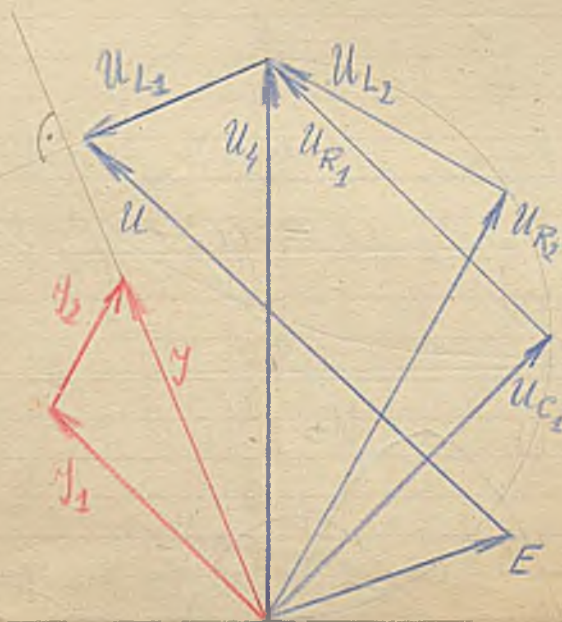


Examin zpodstav elektrotechniki

Narysować ykres Poprosiforuny.



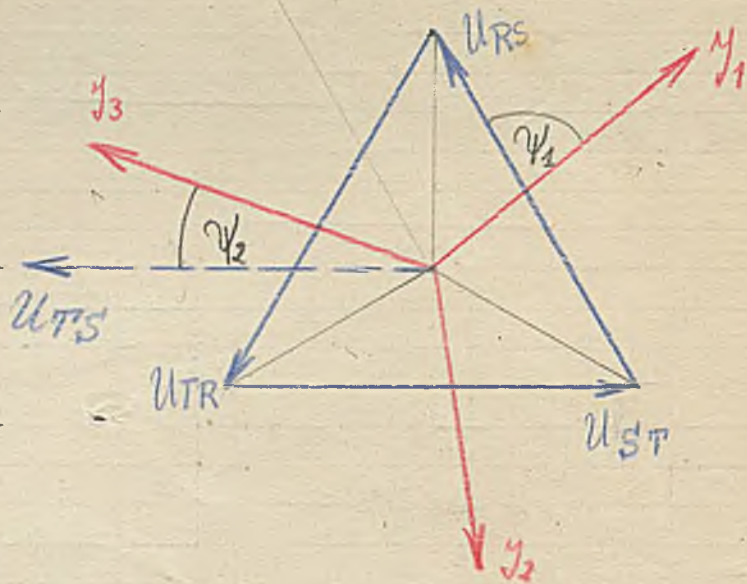
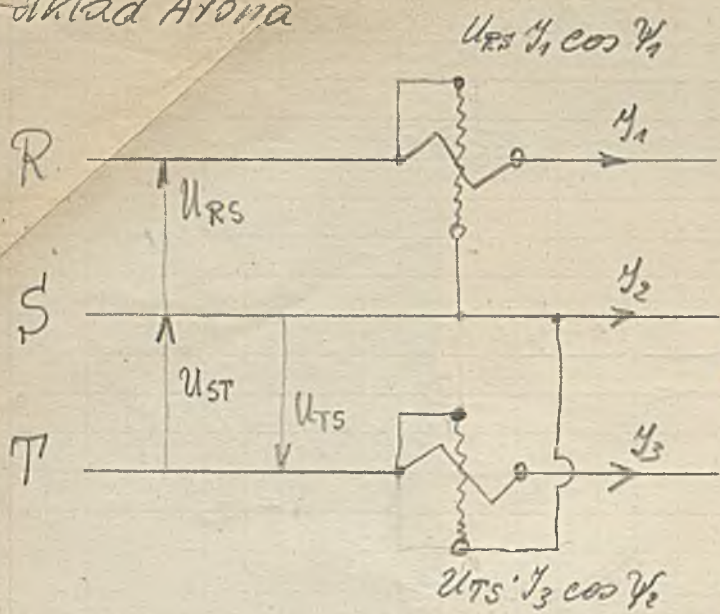
$$E = \frac{C}{V} = m^{-1} \text{ s}^2 \text{ A}^2 \text{ B}^2$$



0,040
0,4

3/50

Wkład Arona



$$P_H = P_{H1} + P_{H2}$$

$$P_H = U_{RS} I_1 \cos \psi_1 + U_{TS} I_3 \cos \psi_2$$

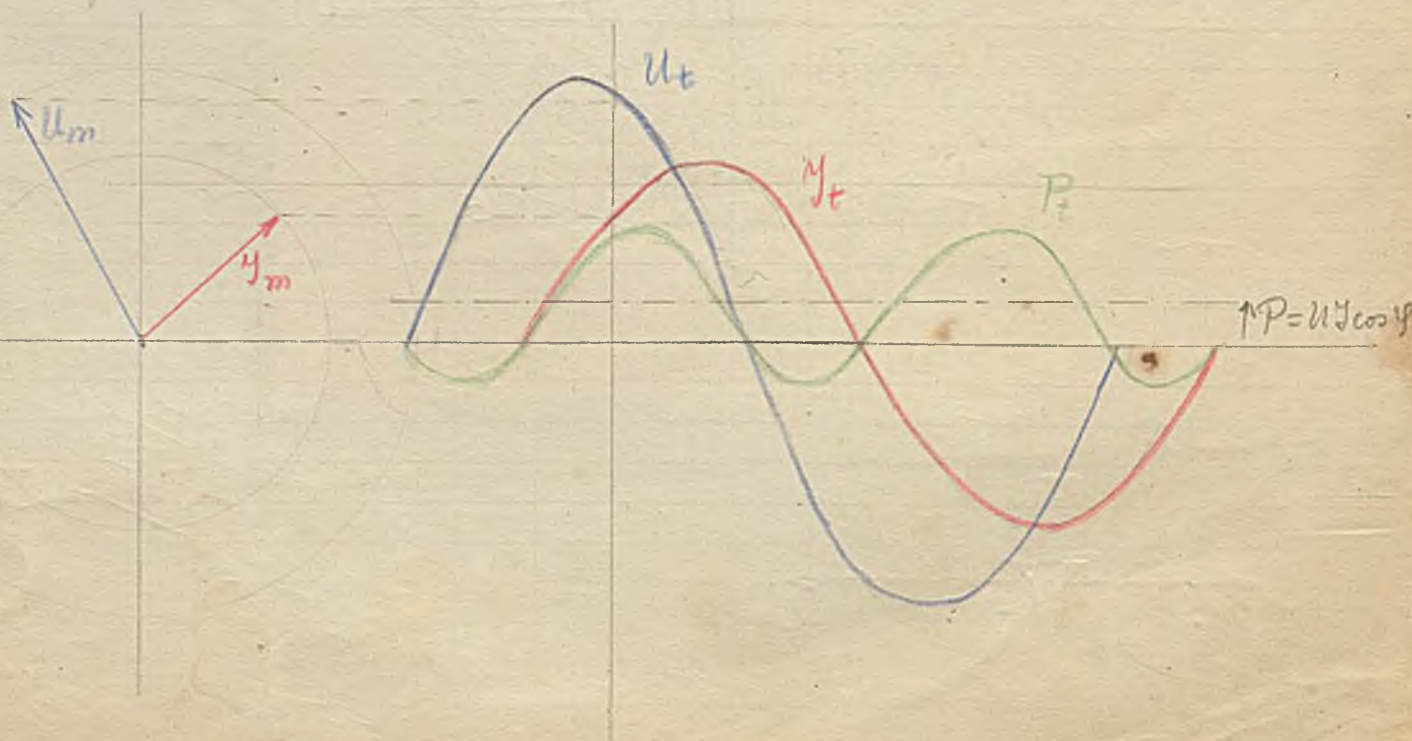
$$P_b = U_{RS} I_1 \sin \psi_1 + U_{TS} I_3 \sin \psi_2$$

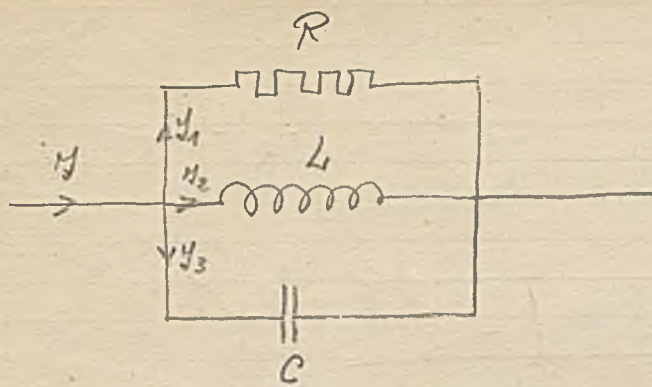
Symbolicznie $\hat{P} = \hat{U} \cdot \hat{I}$

$$\hat{P}_H = \hat{U}_{RS} \cdot \hat{I}_1 + \hat{U}_{TS} \cdot \hat{I}_3$$

Obliczyć moc u wartości średniej

$$P = \frac{1}{T} \int_0^T P_t dt = \frac{1}{T} \int_0^T U_t I_t dt = U I \cos \varphi + \underbrace{U I \sin(2\omega t + \alpha + \beta - \frac{\pi}{2})}_{=0}$$





$$X_L = X_C \quad \text{резонанс}$$

$$\omega L = \frac{1}{\omega C}$$

1) Напряжение выходов произвольно

$$U = Y_2 L \omega \quad Y_2 = \frac{U}{L \omega}$$

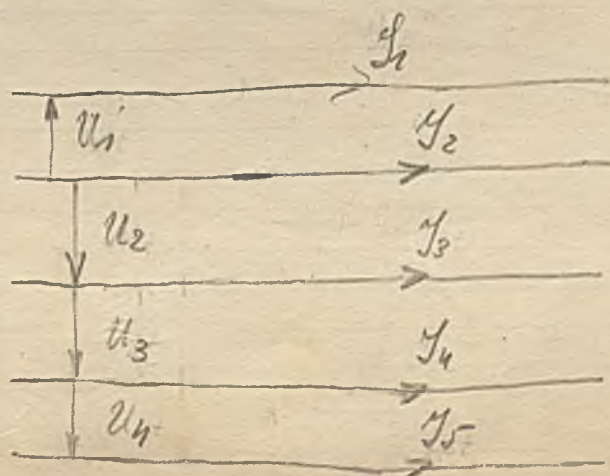
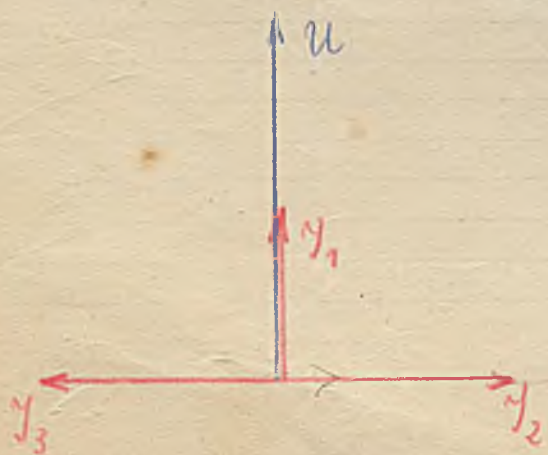
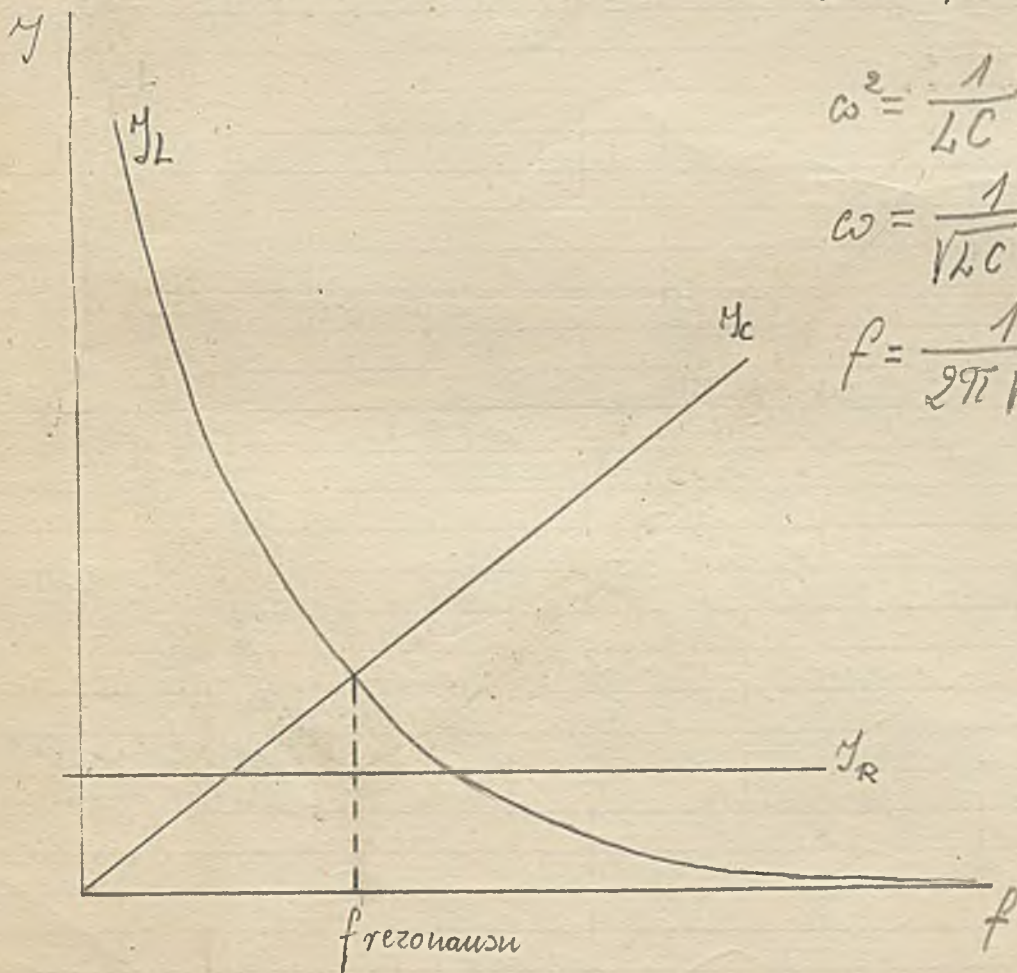
$$U = Y_3 \frac{1}{C \omega} \quad Y_3 = U C \omega$$

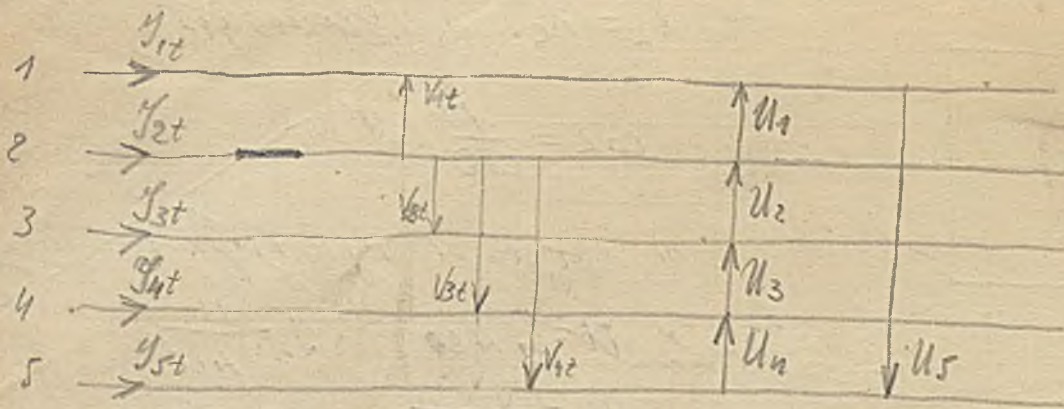
$$U = Y_1 R \quad Y_1 = \frac{U}{R}$$

$$\omega^2 = \frac{1}{LC}$$

$$\omega = \frac{1}{\sqrt{LC}} \quad \omega = 2\pi f$$

$$f = \frac{1}{2\pi \sqrt{LC}}$$





$$P = \frac{1}{T} \int_0^T P_t dt = \frac{1}{T} \int_0^T v_{1t} y_{1t} dt + \frac{1}{T} \int_0^T v_{2t} y_{2t} dt + \frac{1}{T} \int_0^T v_{3t} y_{3t} dt + \frac{1}{T} \int_0^T v_{4t} y_{4t} dt$$

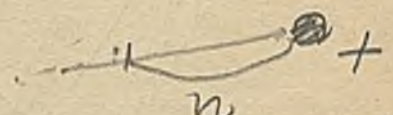
$$P_t = v_{1t} y_{1t} + v_{2t} y_{2t} + v_{3t} y_{3t} + v_{4t} y_{4t} = P_{1t} + P_{2t} + P_{3t} + P_{4t}$$

$$W_{6a} = \int_0^a K dx$$

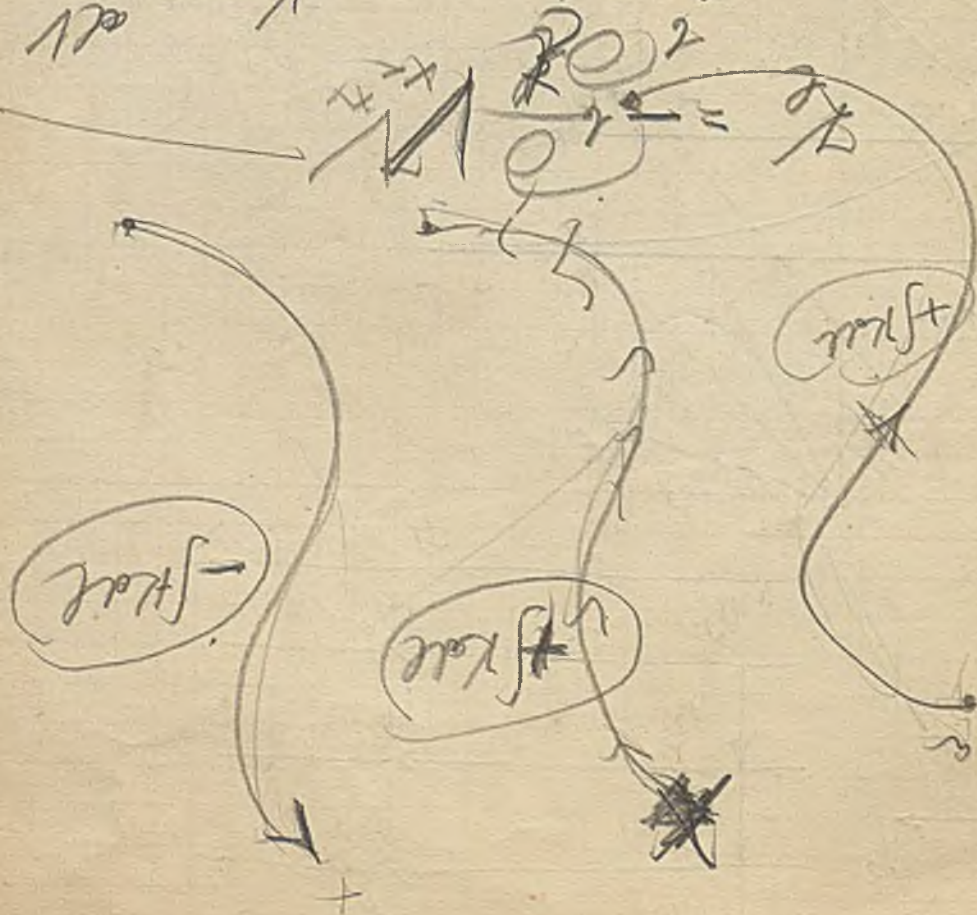
$$W_a = \int_{-\infty}^a K dx$$

$$K = -\frac{dV}{dx}$$

$$\frac{dV}{dx} = K$$



$$dV = dU$$



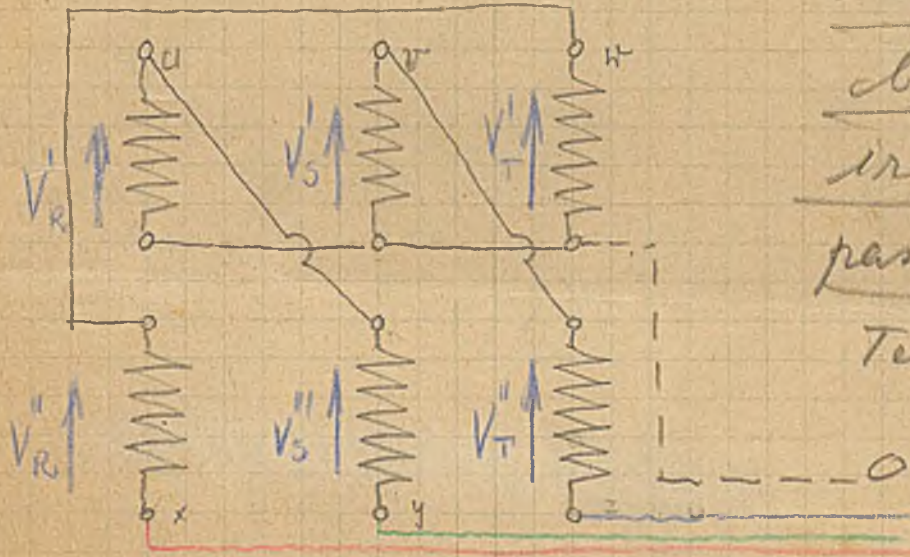
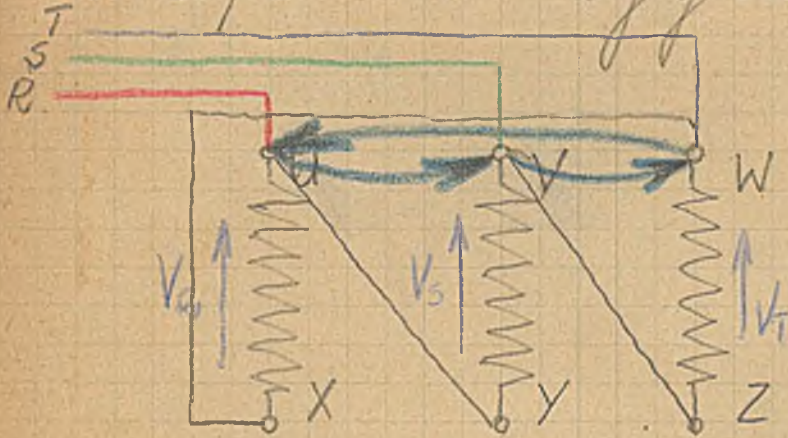
$$W_{AB} = -\int_A^B K dx = -(V_A - V_B)$$

Examinu ustny

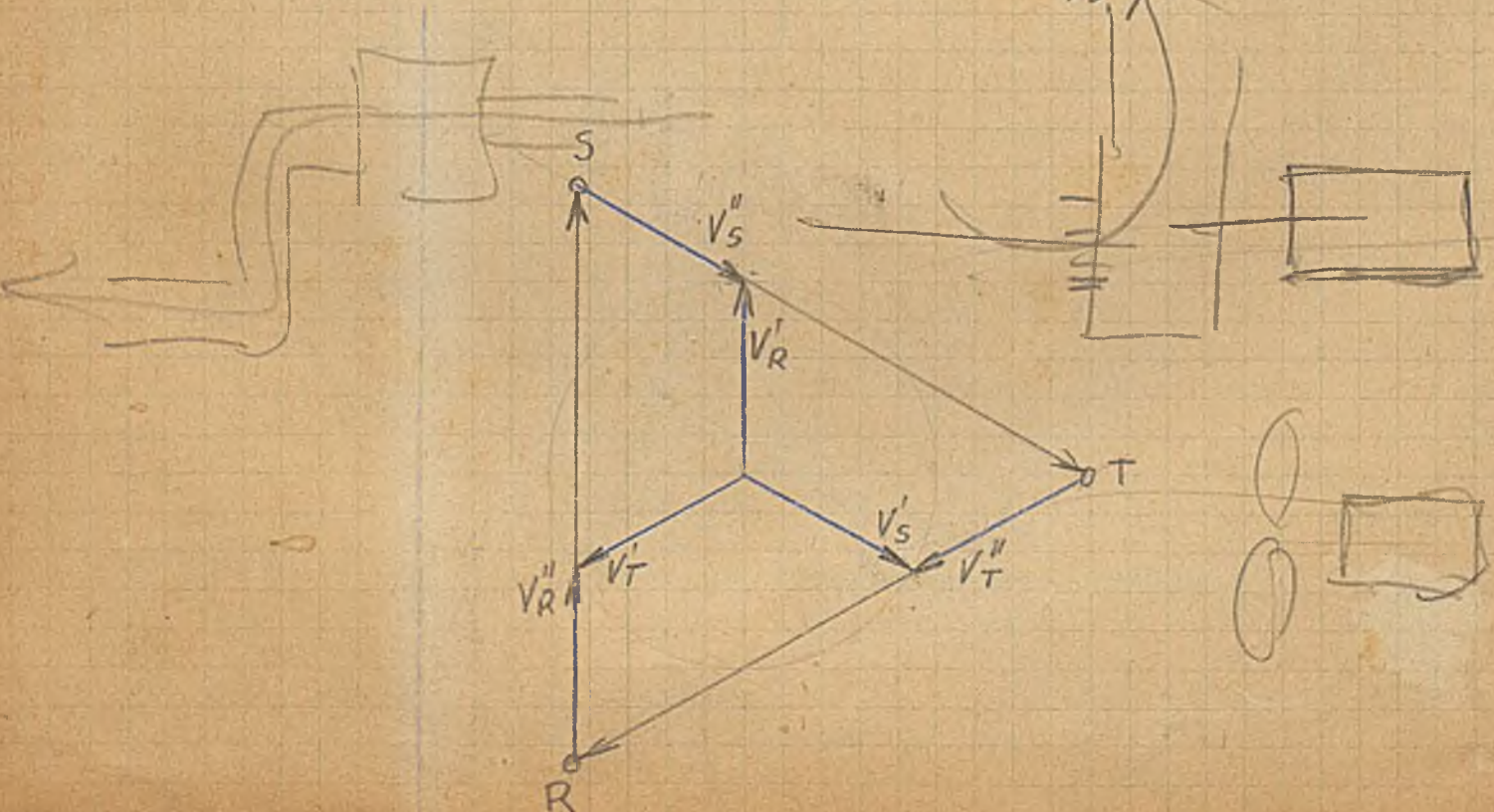
Fiolthowski
Lysard.

Podstawa Elektrotechniki

Trzafo 33 zygza

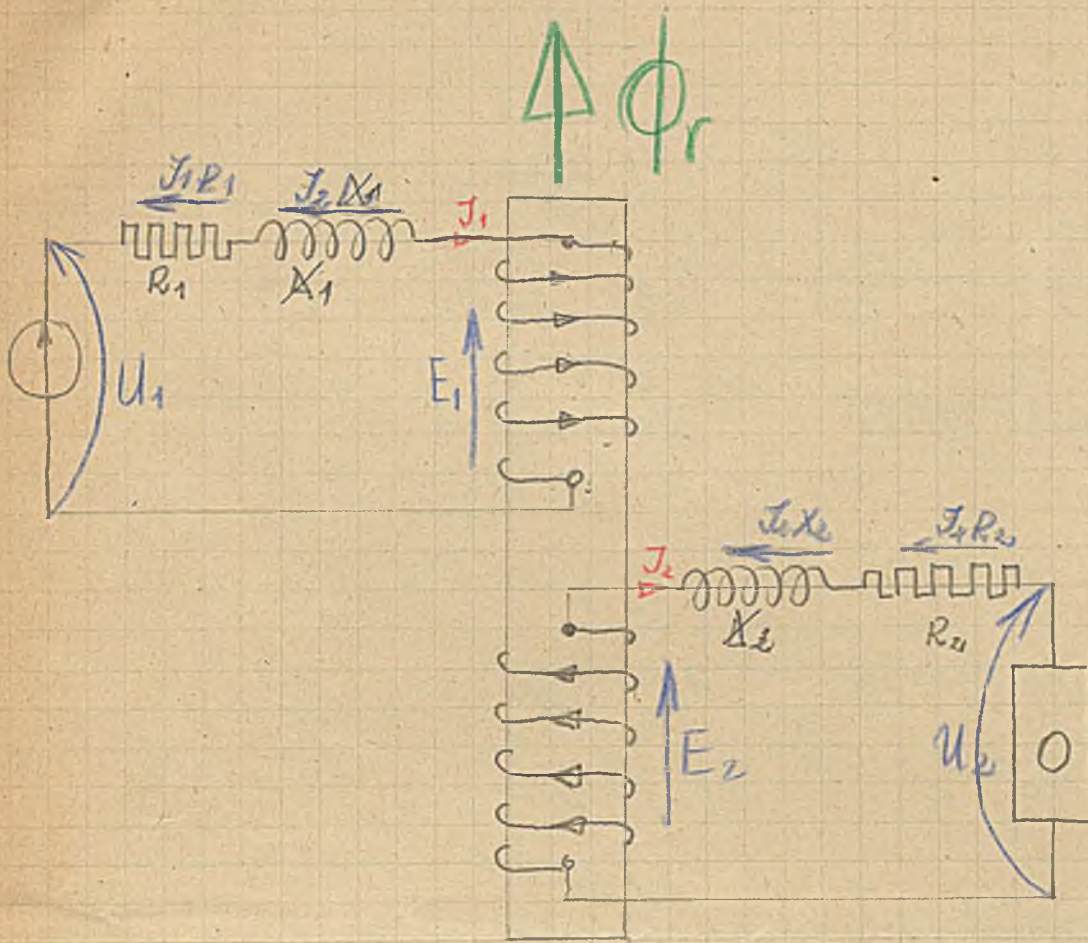


Na cety pole
obnos
2 klasy
mtali nirolarne
zetao
labiny
labulot
reke
pasz abranne
 Tehnyge (prowe
 i koutomowoy)

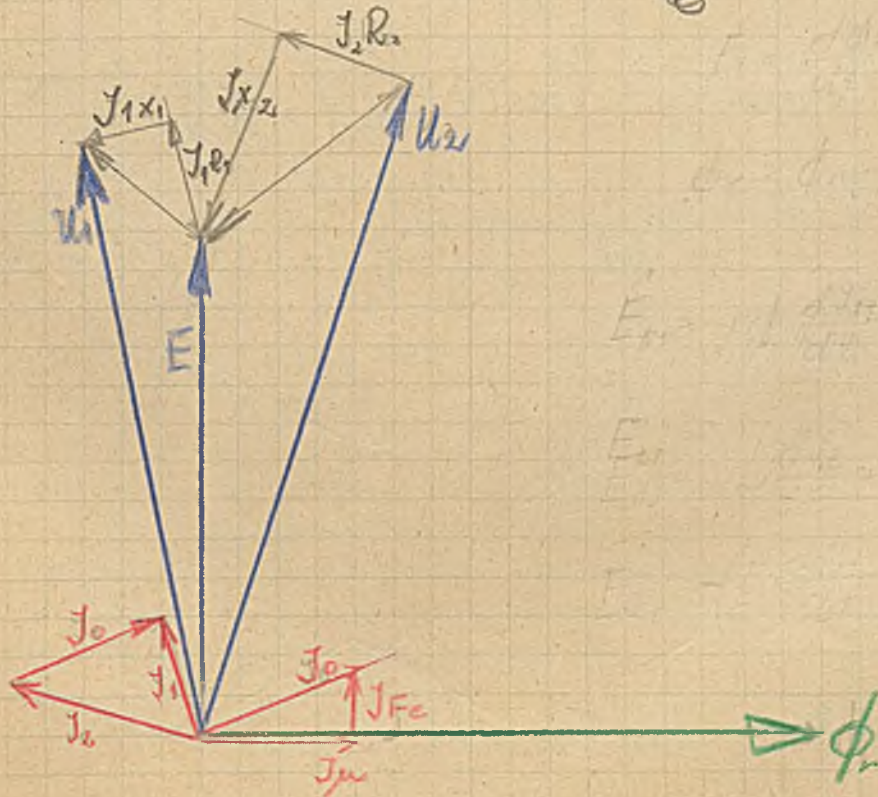


Transformator

Handwritten notes in red ink, partially illegible.



$U_2 = I_2 R_2$



6

Handwritten notes in blue ink, partially illegible.

$$\hat{U}_1 = \hat{I}_1 R_1 + \hat{I}_1 \hat{X}_1 + \hat{E}_1$$

$$\hat{E}_1 = \left[L_1 \frac{d\hat{I}_1}{dt} - M \frac{d\hat{I}_2}{dt} \right]$$

$$\hat{U}_2 = \hat{E}_2 - \hat{I}_2 \hat{X}_2 - \hat{I}_2 R_2$$

$$\hat{E}_2 = \left[L_2 \frac{d\hat{I}_2}{dt} - M \frac{d\hat{I}_1}{dt} \right]$$

$$\hat{U}_1 = \hat{I}_1 R_1 + \hat{I}_1 \hat{X}_1 + L_1 \frac{d\hat{I}_1}{dt} - M \frac{d\hat{I}_2}{dt}$$

$$\hat{U}_2 = - \left[L_2 \frac{d\hat{I}_2}{dt} - M \frac{d\hat{I}_1}{dt} \right] - \hat{I}_2 \hat{X}_2 - \hat{I}_2 R_2$$

$$\hat{E}_e = \frac{d\phi_e}{dt} \cdot z \cdot 10^{-8} \text{ V} \quad ; \quad \phi_e = \phi_m e^{j\omega t}$$

$$\hat{E}_e = \phi_m j\omega z \cdot 10^{-8} \text{ V} = \phi_m j\omega z \cdot 10^{-8} e^{j\omega t}$$

$$\hat{E}_e = \phi_m j\omega z \cdot e^{j\omega t} \cdot 10^{-8} \text{ V}$$

$$\hat{E}_m = \phi_m \frac{j\omega z}{\sqrt{2}} e^{j\omega t} \cdot 10^{-8} \text{ V}$$

$$k = \frac{z_1}{z_2} \text{ współczynnik transformacji}$$

Dla wartości chwilowych

$$U_{1t} = I_{1t} R_1 + I_{1t} X_1 + \left[L_1 \frac{dI_{1t}}{dt} - M \frac{dI_{2t}}{dt} \right]$$

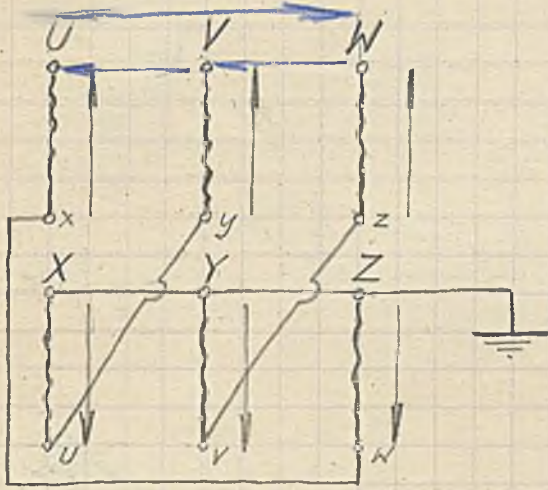
$$U_{2t} = - \left[L_2 \frac{dI_{2t}}{dt} - M \frac{dI_{1t}}{dt} \right] - I_{2t} X_2 - I_{2t} R_2$$

9.12.1949 r.

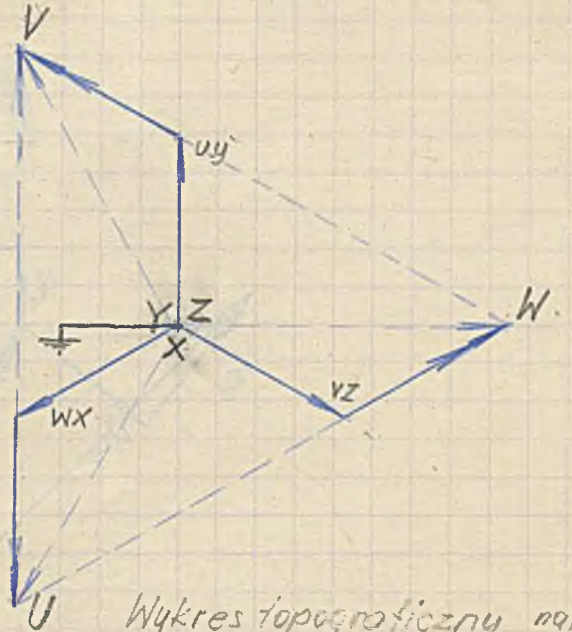
Pracownia Jan
SEM. V. *doła*

Examin ustny z Podstaw elektrotechniki

1.)

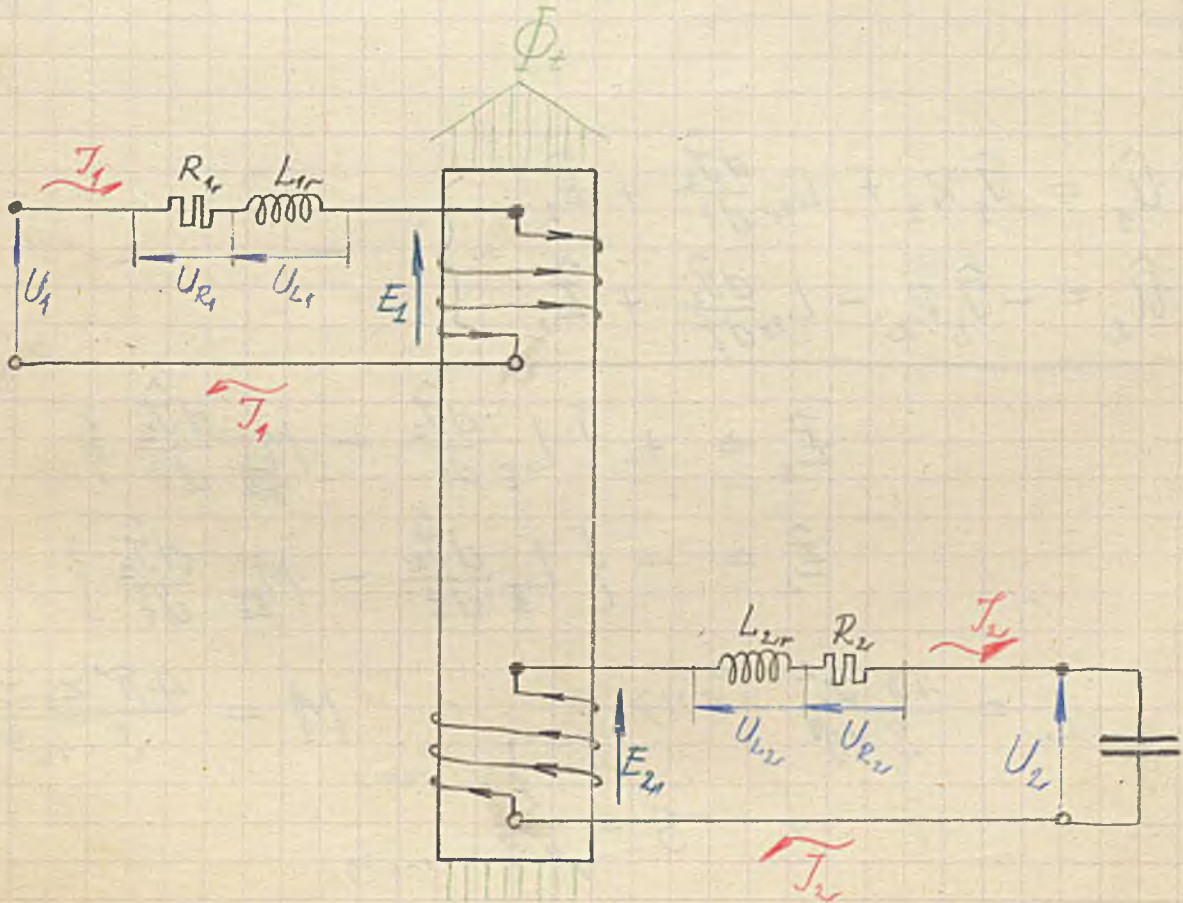


Schemat połączeń uzwojenia wtórnego transformatora 3-faz pot. w zygzał



Wykres topograficzny napięć w uzwojeniu wt. tr pot. w zygzał (dla układu symetrycznego).

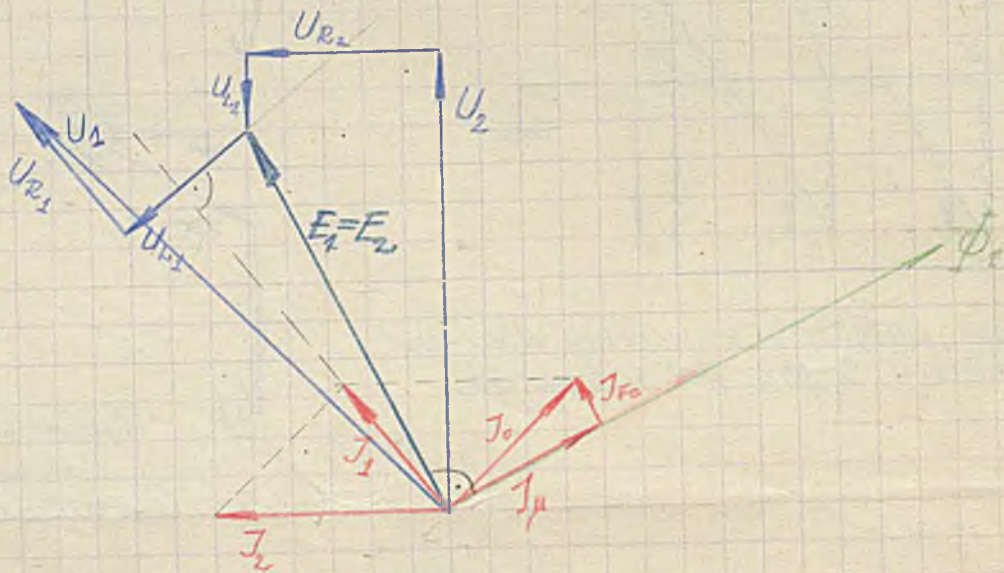
2.)



Schemat połączeń transformatora jednofazowego obciąż. pojemnością.

dobry

Wykres transformatora obc. pojemnością



$$\left. \begin{aligned} \hat{U}_1 &= \hat{I}_1 R_1 + L_{1r} \frac{d\hat{I}_1}{dt} + \hat{E}_1 \\ \hat{U}_2 &= -\hat{I}_2 R_2 - L_{2r} \frac{d\hat{I}_2}{dt} + \hat{E}_2 \end{aligned} \right\}$$

$$\hat{E}_1 = + \left\{ L_I \frac{d\hat{I}_1}{dt} - M_{II} \frac{d\hat{I}_2}{dt} \right\}$$

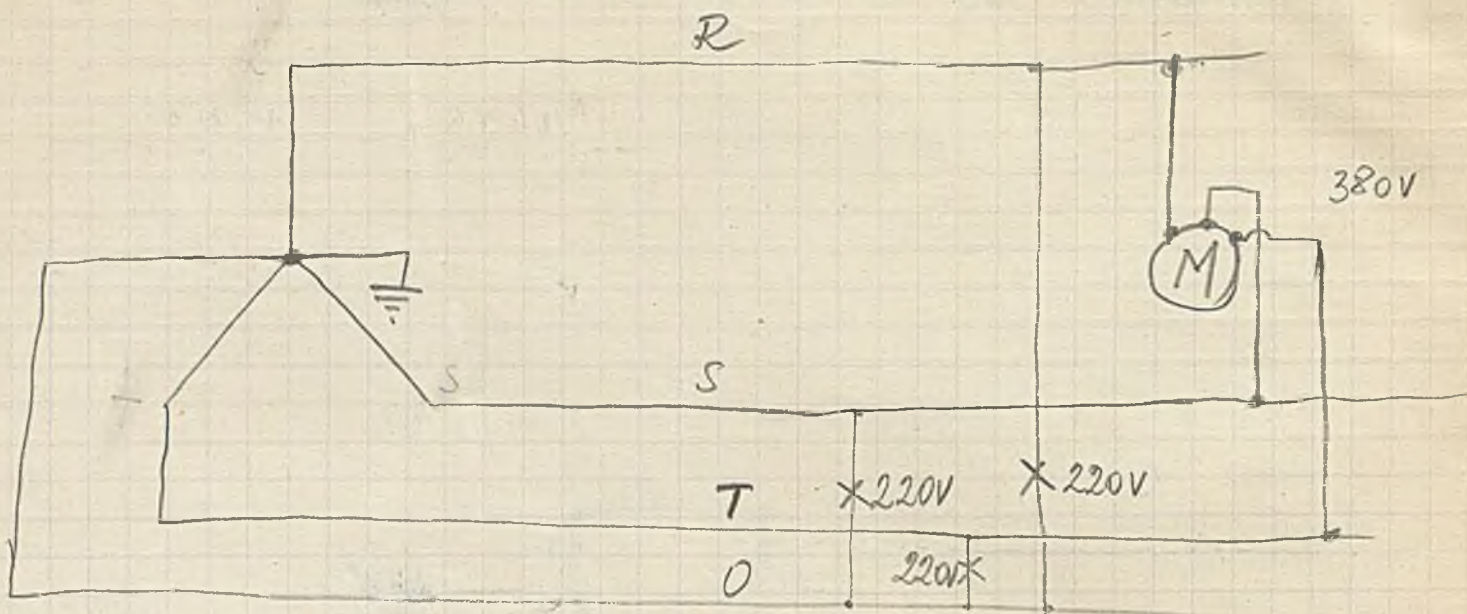
$$\hat{E}_2 = - \left\{ L_{II} \frac{d\hat{I}_2}{dt} - M_I \frac{d\hat{I}_1}{dt} \right\}$$

$$L = \frac{4\pi z^2}{S \cdot 10^9} \quad \langle H \rangle$$

$$M = \frac{4\pi z_1 z_2}{S \cdot 10^9} \quad \langle H \rangle$$

$$S = \frac{l}{\mu s} \quad \begin{matrix} \langle cm \rangle \\ \langle cm^2 \rangle \end{matrix}$$

$$L_I = L_{II} = L \quad ; \quad M_I = M_{II} = M \quad ; \quad z_1 = z_2$$



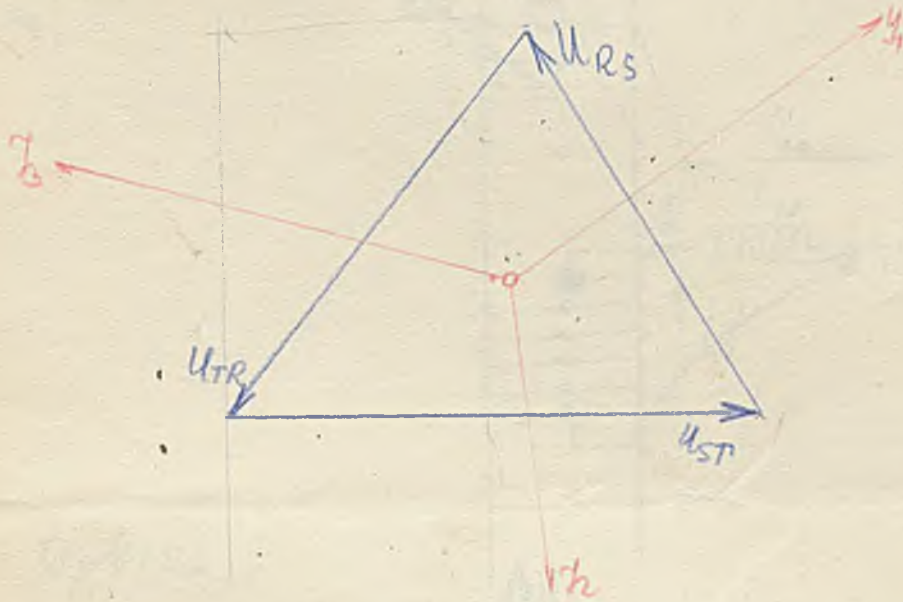
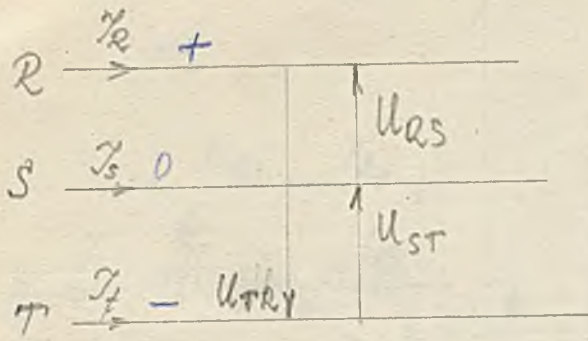
λ 380 V

Δ 220 V

Δ 380 V

λ 660 V

0,1 A



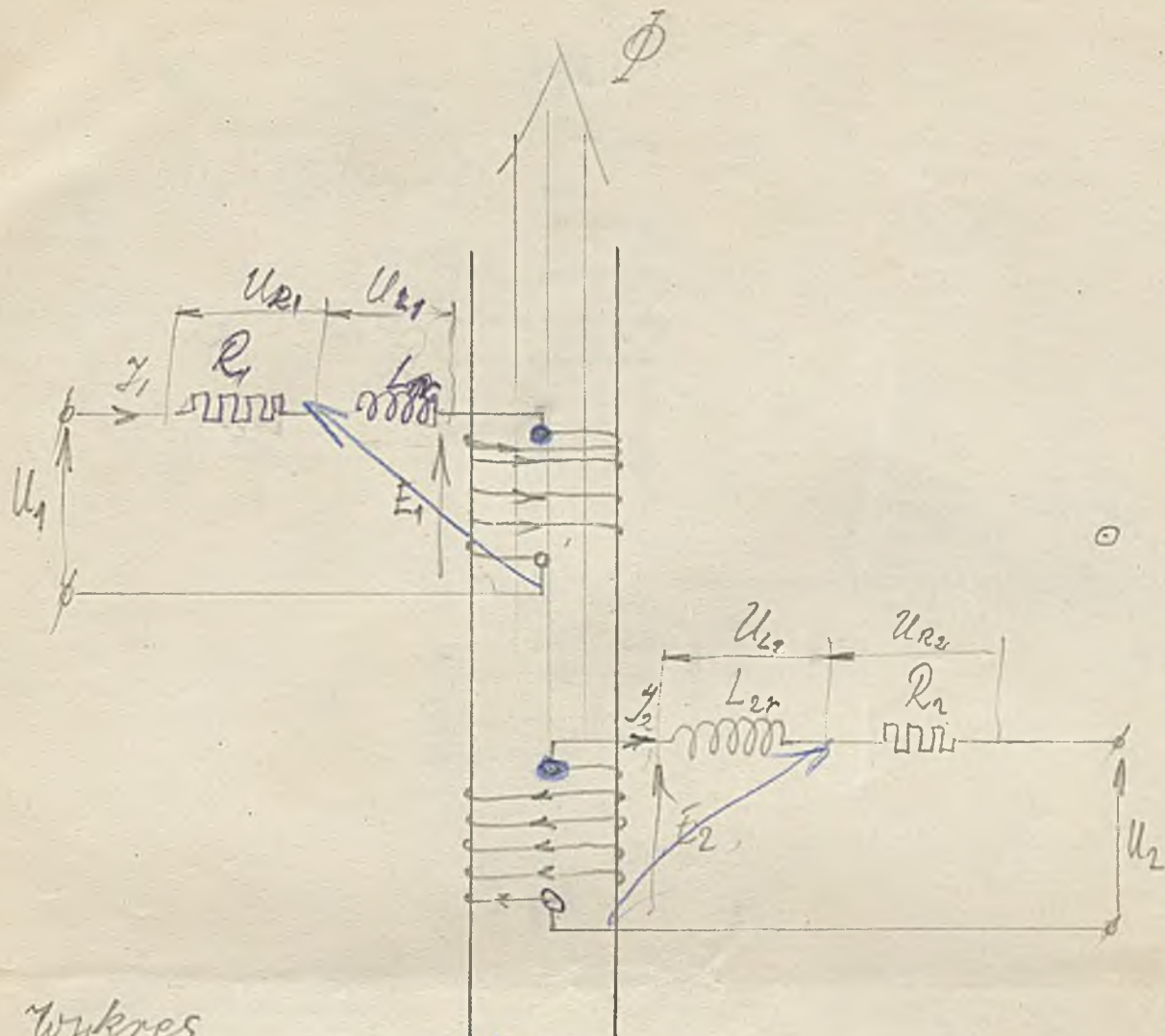
$$U_1 = E_1 + \gamma_1 R$$

$$U_2 = E_2 - \gamma_2 R_2$$

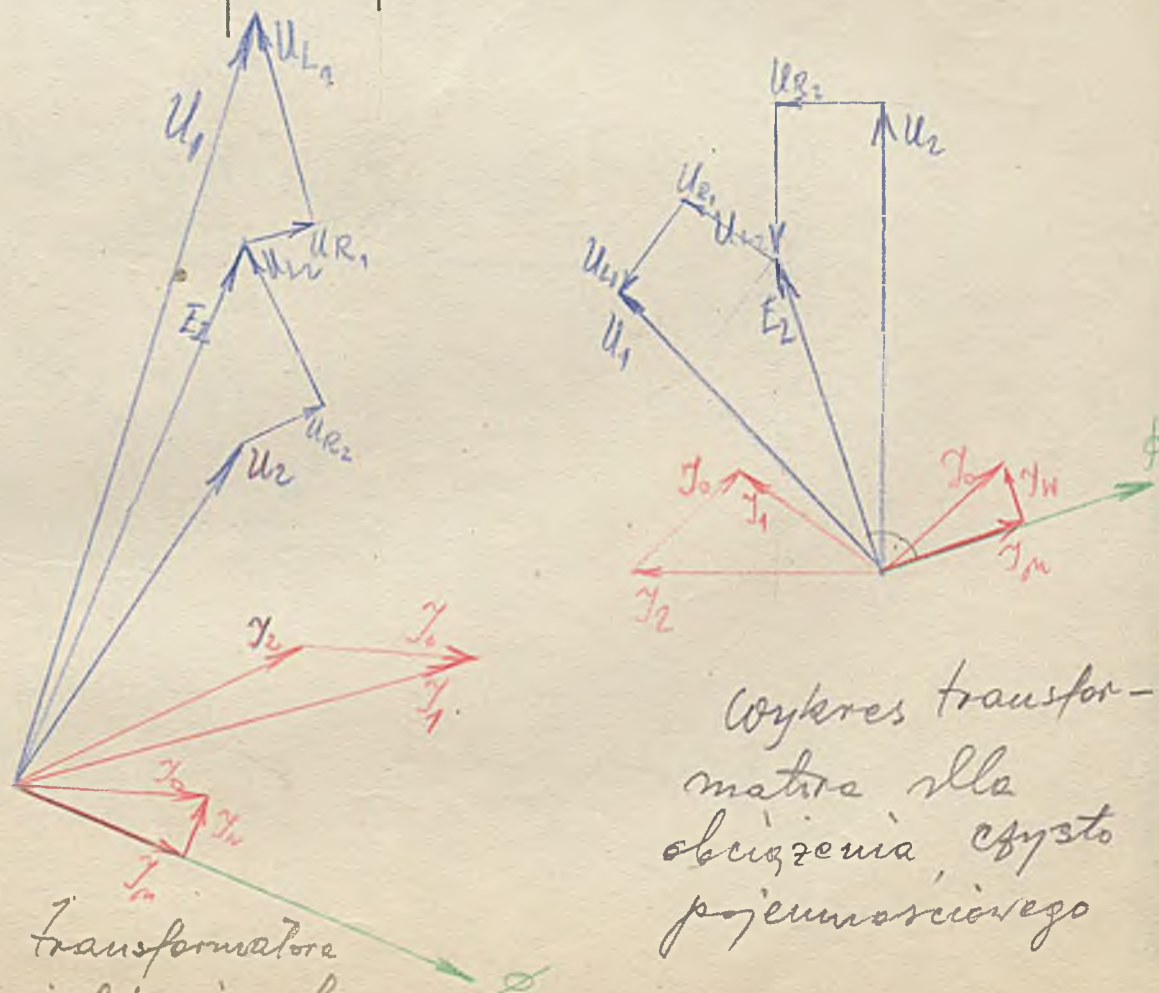
$$\hat{U}_1 = \hat{E}_1 + \hat{\gamma}_1 \hat{L}_1$$

$$\hat{U}_2 = \hat{E}_2 - \hat{\gamma}_2 \hat{L}_2$$



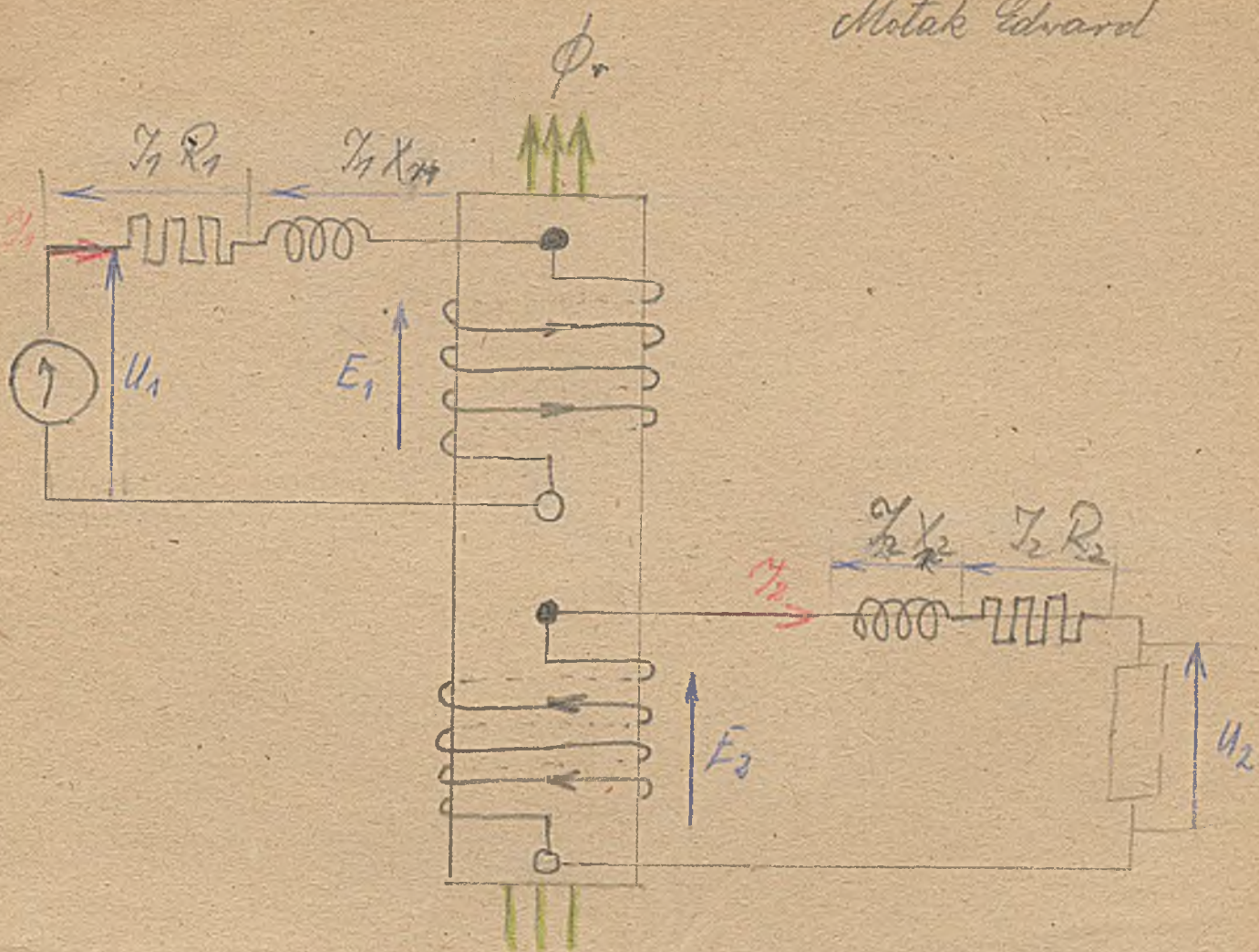


Wykres



Wykres dla transformatora o obciążeniu indukcyjno-obrotowym

Wykres transformatora dla obciążenia czysto pojemnościowego



$$U_{1t} - I_{1t} R - L_{1r} \frac{dI_{1t}}{dt} - E_{1t} = 0$$

$$U_{2t} + I_{2t} R + L_{2r} \frac{dI_{2t}}{dt} - E_{2t} = 0$$

$$\hat{U}_1 - \hat{I}_1 R_1 - \hat{I}_1 X_{1r} - \hat{E}_1 = 0$$

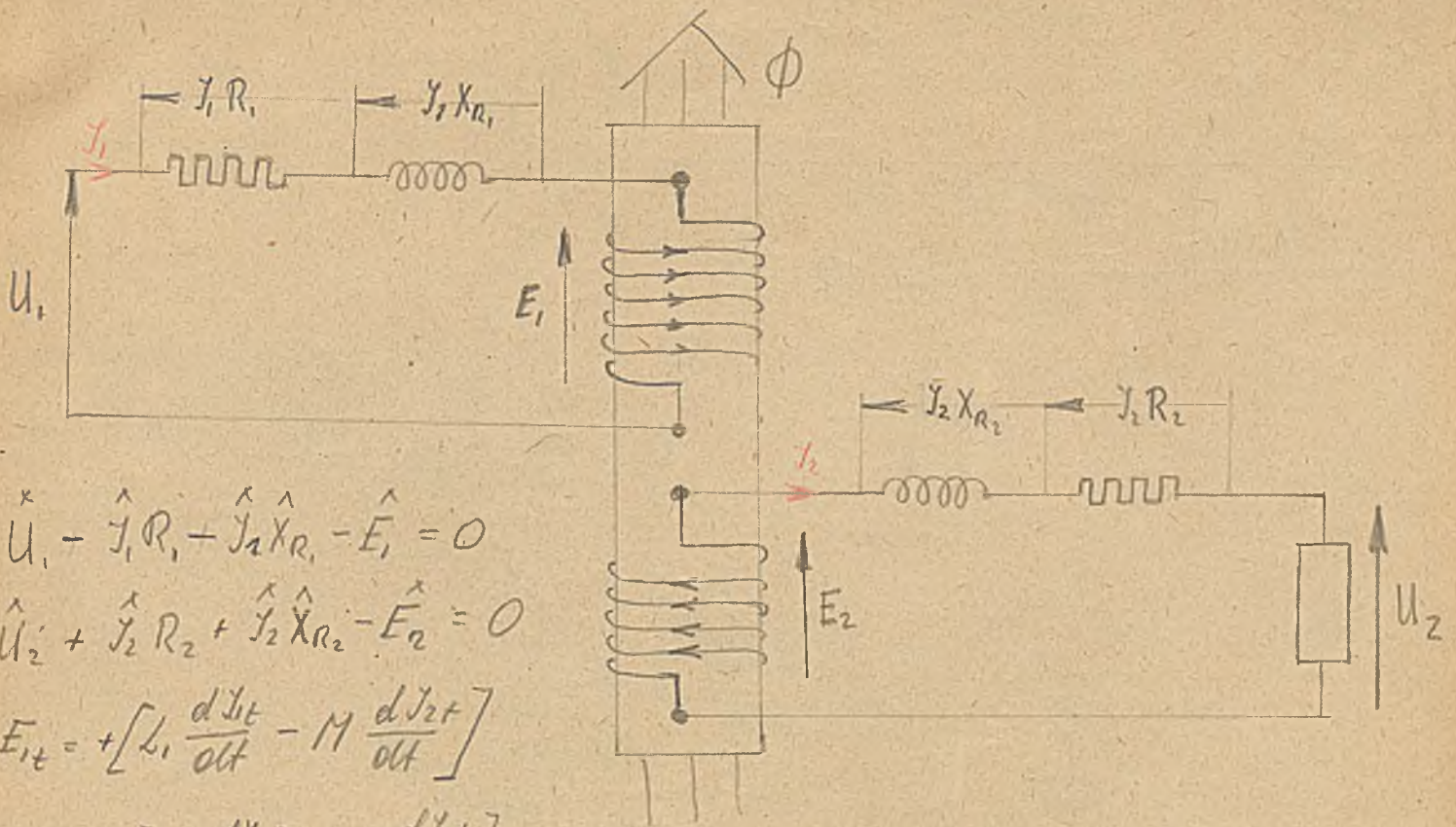
$$\hat{U}_2 + \hat{I}_2 R_2 + \hat{I}_2 X_{2r} - \hat{E}_2 = 0$$

$$\hat{I}_1 X_{1r} = j\omega L_{1r} \hat{I}_1$$

$$\hat{Z}_1 = R_1 + jL_{1r}\omega$$

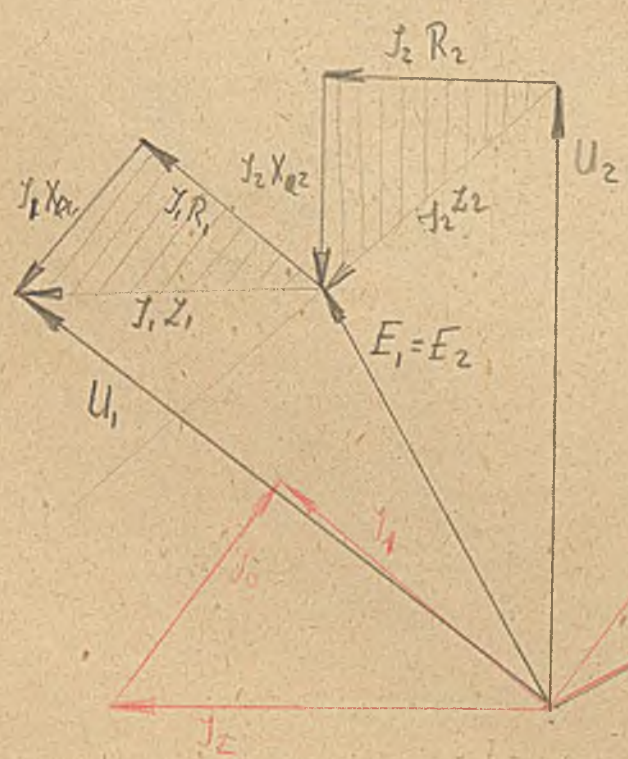
$$\hat{Z}_2 = R_2 + jL_{2r}\omega$$

$$\bar{F} = \frac{0,49}{S} (\gamma_1 z_1 - \gamma_2 z_2)$$



$$\begin{aligned} \hat{U}_1 - \hat{I}_1 R_1 - \hat{I}_1 X_{R1} - \hat{E}_1 &= 0 \\ \hat{U}_2 + \hat{I}_2 R_2 + \hat{I}_2 X_{R2} - \hat{E}_2 &= 0 \\ E_{1t} &= + \left[L_1 \frac{dI_{1t}}{dt} - M \frac{dI_{2t}}{dt} \right] \\ E_{2t} &= - \left[L_2 \frac{dI_{2t}}{dt} - M \frac{dI_{1t}}{dt} \right] \end{aligned}$$

$$E = 4,44 \Phi_m f \cdot 2 \cdot 10^{-8} \text{ V}$$



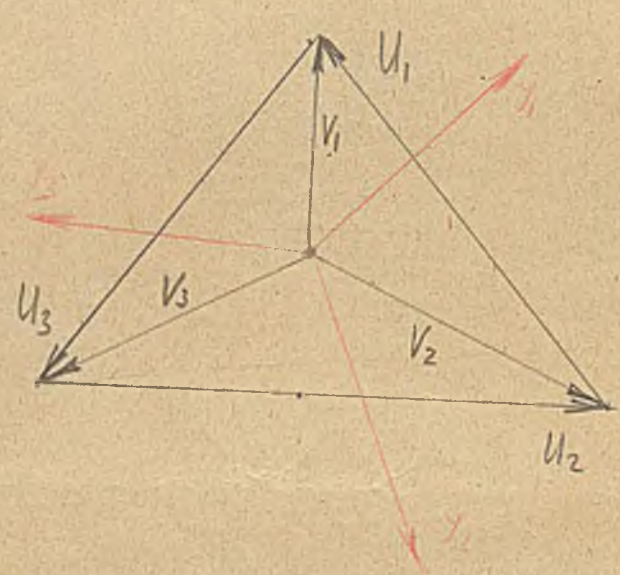
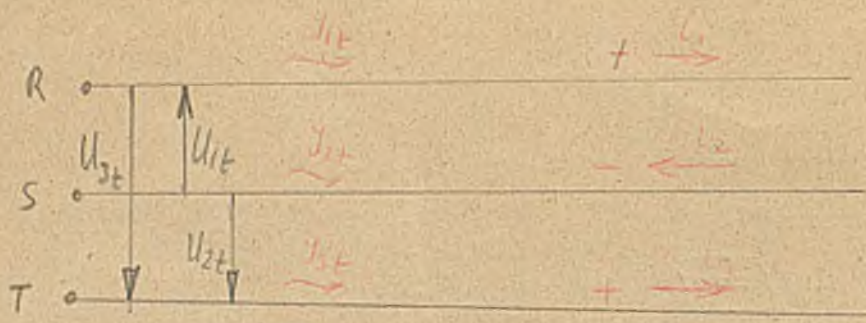
$$X_{R2} = L_{R2} \omega$$

$$\hat{\Phi} = \frac{0,4 \pi}{5} (\hat{I}_1 X_{L1} - \hat{I}_2 X_{L2})$$

$$\begin{aligned} \hat{U}_1 &= \hat{E}_1 + \hat{I}_1 (R_1 + X_{R1}) = \hat{E}_1 + \hat{I}_1 \hat{Z}_1 & \hat{Z}_1 &= R_1 + j L_{R1} \omega \\ \hat{U}_2 &= \hat{E}_2 - \hat{I}_2 (R_2 + X_{R2}) = \hat{E}_2 - \hat{I}_2 \hat{Z}_2 & \hat{Z}_2 &= R_2 + j L_{R2} \omega \end{aligned}$$

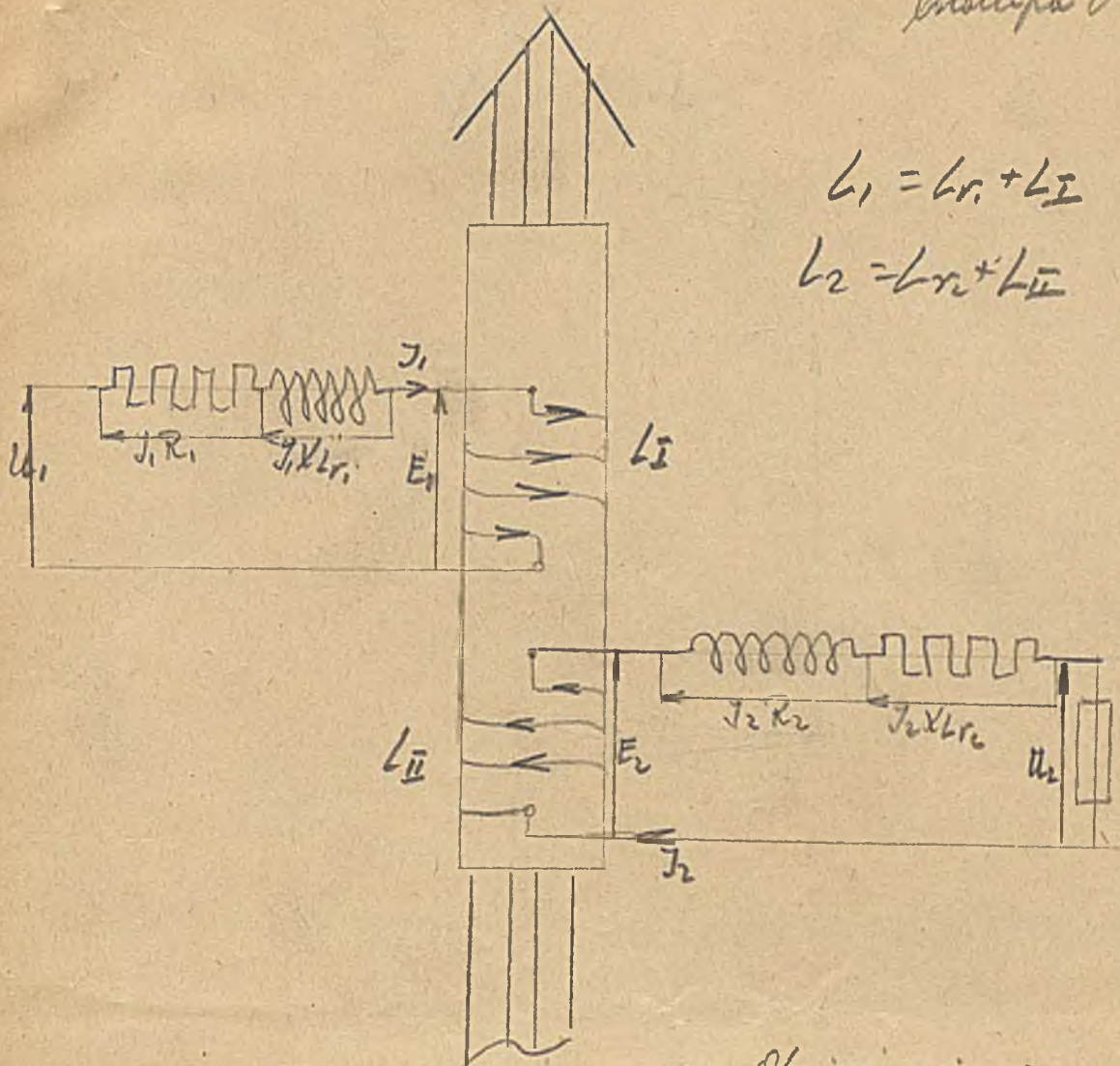
$$\boxed{\hat{U}_1 = \hat{E}_1 + \hat{I}_1 \hat{Z}_1}$$

$$\boxed{\hat{U}_2 = \hat{E}_2 - \hat{I}_2 \hat{Z}_2}$$

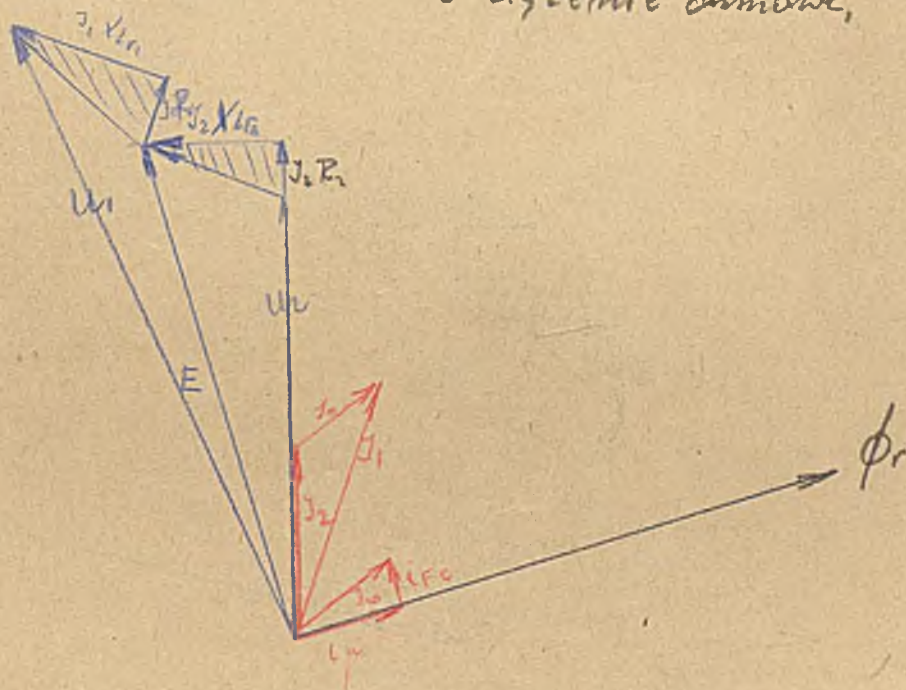


$$L_1 = L_{r1} + L_{II}$$

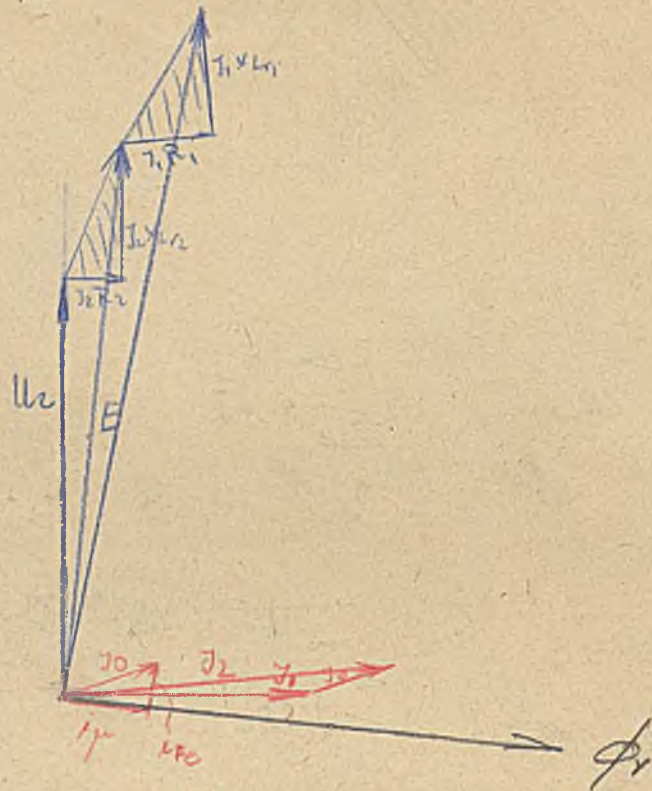
$$L_2 = L_{r2} + L_{II}$$



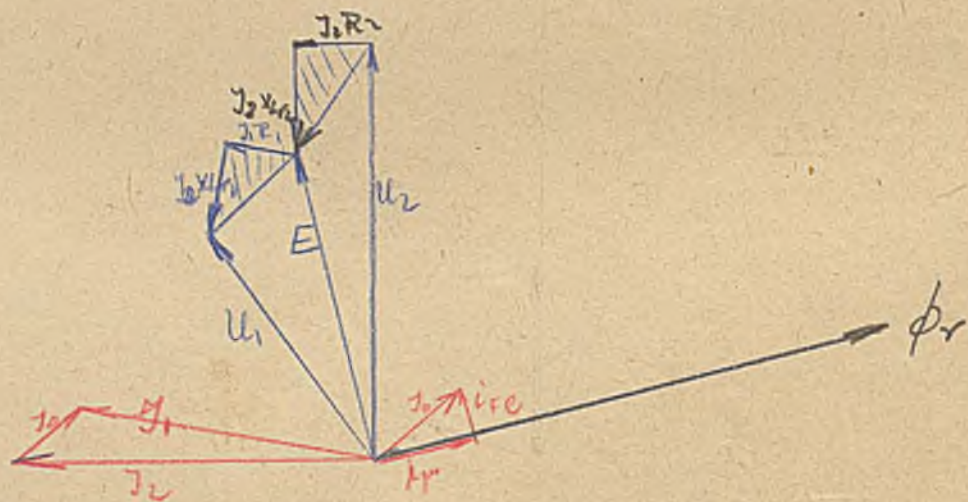
Obciążenie obrotowe,



Obciążenie indukcyjne,

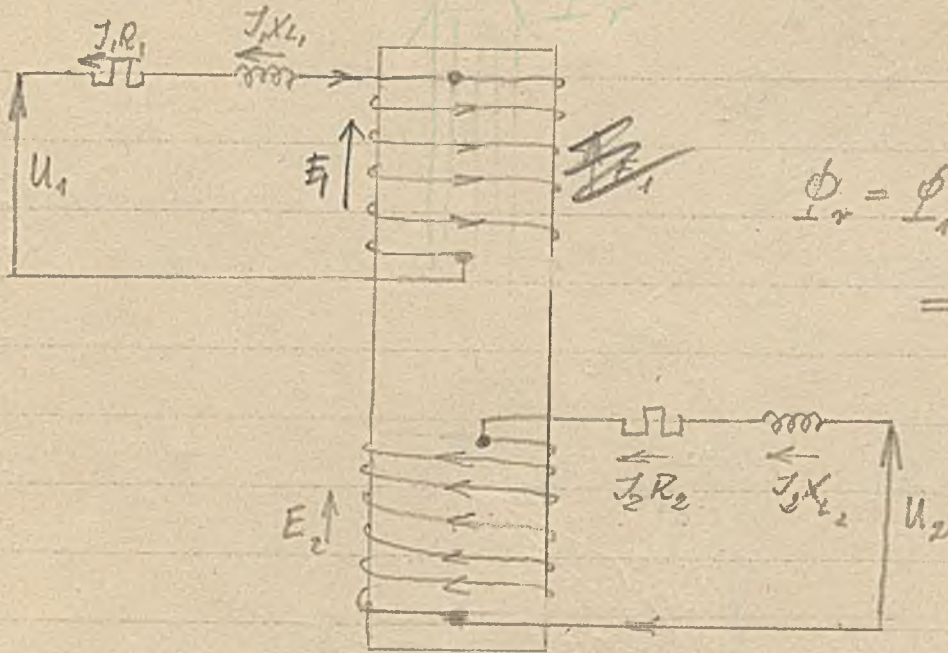


Obciążenie pojemnościowe.



3

Andriy Zubov



$$\Phi = \Phi_1 - \Phi_2 = \frac{0.4 \pi I_1}{5} - \frac{0.45 I_2}{5}$$

$$= \frac{0.452}{5} (I_1 - I_2)$$

I_0 - proud bezpe
jstovogo

o: $U_{1e} = E_1 + I_1 R_1 + L_1 \frac{dI_1}{dt}$ }

w: $U_{2e} = E_2 - I_2 R_2 - L_2 \frac{dI_2}{dt}$ }

$$E_1 = \left[L_1 \frac{dI_1}{dt} - M \frac{dI_2}{dt} \right]$$

$$E_2 = - \left[L_2 \frac{dI_2}{dt} - M \frac{dI_1}{dt} \right]$$

$$U_1 = I_1 R_1 + \left[L_1 \frac{dI_1}{dt} - M \frac{dI_2}{dt} \right] + L_1 \frac{dI_1}{dt}$$

$$\hat{U}_1 = \hat{I}_1 R_1 + L_{r1} \frac{d\hat{I}_1}{dt} + \left[L_1 \frac{d\hat{I}_1}{dt} - M \frac{d\hat{I}_2}{dt} \right]$$

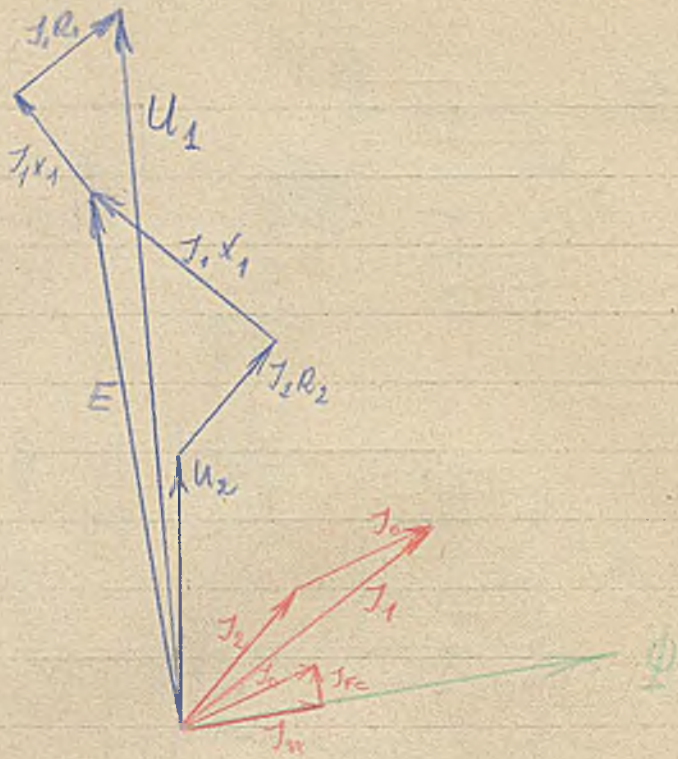
$$\hat{U}_1 = \hat{I}_1 R_1 + j\omega L_{r1} \hat{I}_1 + [j\omega L_1 \hat{I}_1 - j\omega M \hat{I}_2]$$

$$\hat{U}_1 = \hat{I}_1 R_1 + j\omega L_{r1} \hat{I}_1 + j\omega [L_1 \hat{I}_1 - M \hat{I}_2] \quad \text{I}$$

$$\hat{U}_2 = -\hat{I}_2 R_2 - L_{r2} \frac{d\hat{I}_2}{dt} - \left[L_2 \frac{d\hat{I}_2}{dt} - M \frac{d\hat{I}_1}{dt} \right]$$

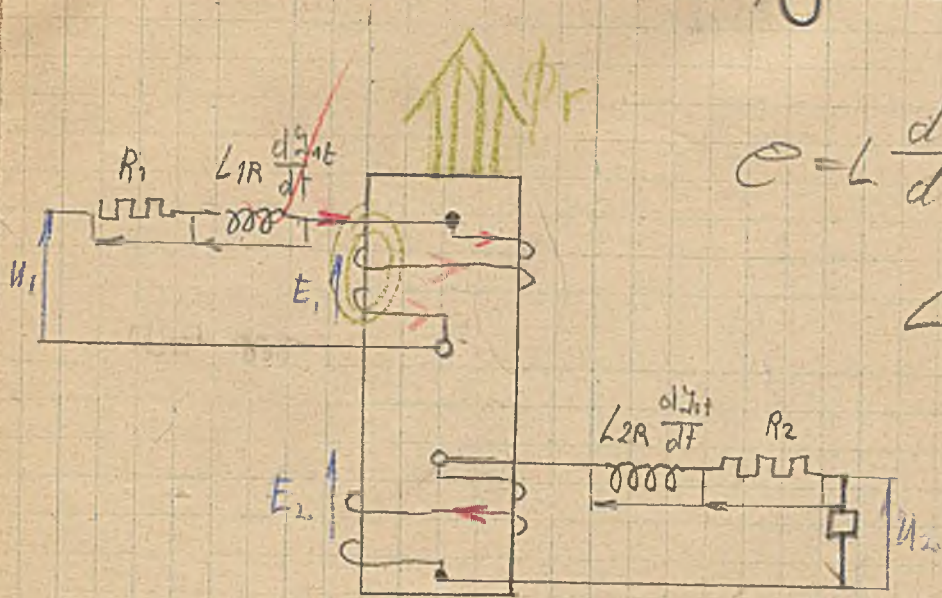
$$\hat{U}_2 = -\hat{I}_2 R_2 - j\omega L_{r2} \hat{I}_2 - j\omega [L_2 \hat{I}_2 - M \hat{I}_1] \quad \text{II}$$

$$\hat{E}_m = \hat{E}_1 = \hat{E}_2 = 4.44 j \Phi_m 9.2 \cdot 10^3$$



- U_2
- J_2
- $J_2 R_2$
- $J_2 x_2$
- E
- J_m
- J_{Fe}
- J_0
- J_1
- $J_1 x_1$
- $J_1 R_1$
- U_1

Рівняння лінійного трансформатора.



$$e = L \frac{dI}{dt}$$

$$L = \frac{4.44 \cdot 9.7 \cdot 2 \cdot 10^{-8}}{5}$$

$$\frac{L}{5 \cdot 10^{-8}}$$

$$U_{1t} - I_{1t} R_1 - L_{1R} \frac{dI_{1t}}{dt} - E_{1t} = 0$$

$$U_{2t} + I_{2t} R_2 + L_{2R} \frac{dI_{2t}}{dt} - E_{2t} = 0$$

$$U_{1t} = E_{1t} + I_{1t} R_1 + L_{1R} \frac{dI_{1t}}{dt}$$

$$I_F = I_m \sin(\omega t + \varphi)$$

$$U_{2t} = E_{2t} - I_{2t} R_2 - L_{2R} \frac{dI_{2t}}{dt}$$

Символічне

$$\hat{U}_1 = \hat{E}_1 + \hat{I}_1 R_1 + \hat{I}_1 \hat{X}_{1R}$$

$$\hat{U}_1 = \hat{E}_1 + \hat{I}_1 R_1 + j\omega L_{1R} \hat{I}_1$$

$$\hat{U}_2 = \hat{E}_2 - \hat{I}_2 R_2 - \hat{I}_2 \hat{X}_{2R}$$

$$\hat{U}_2 = \hat{E}_2 - \hat{I}_2 R_2 - j\omega L_{2R} \hat{I}_2$$

$$E_e = 2 \frac{d\Phi}{dt} \cdot 10^{-8} V$$

$$\Phi_e = \Phi_m \sin \omega t$$

$$E_e = \omega 2 \Phi_m \cos \omega t \cdot 10^{-8}$$

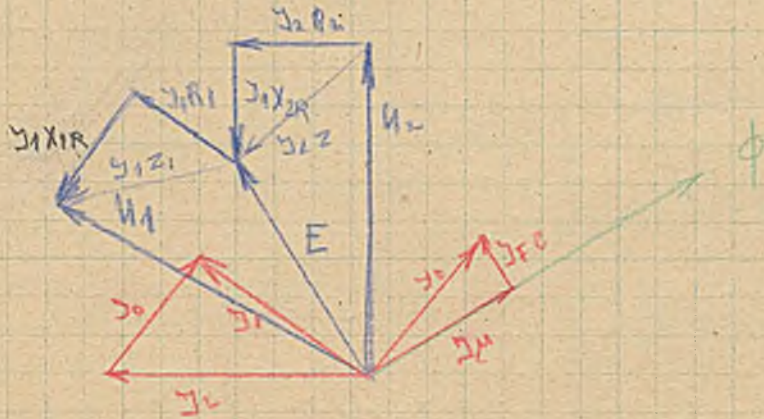
$$E_m = 2\pi f \Phi_m 2 \cdot 10^{-8}$$

$$E = \frac{2\pi}{\sqrt{2}} f \Phi_m 2 \cdot 10^{-8} = 4.44 f \Phi_m 2 \cdot 10^{-8}$$

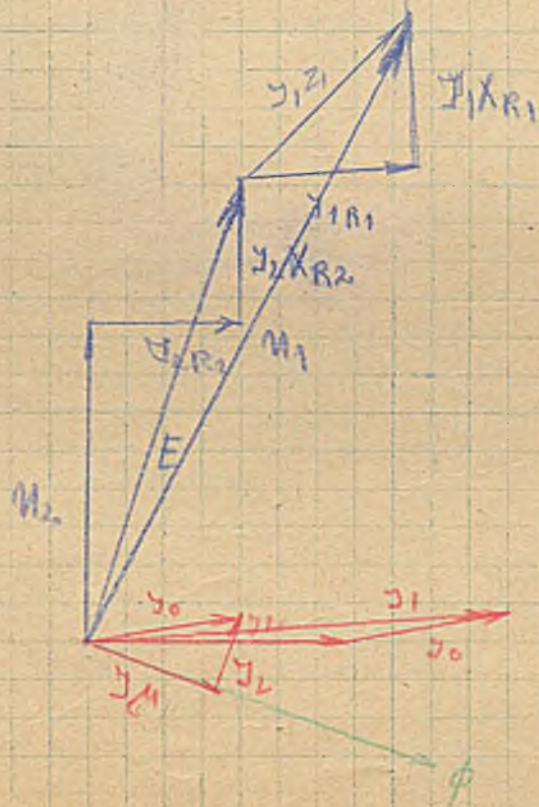
$$\hat{E} = j 4.44 \Phi_m f \cdot 2$$

Wytwarzanie dla etc. pojemu.

Obs. pojedynczo



Obciążenie indukcyjne



$$E_1 = j4544 \phi_m z_1 10^{-8}$$

$$E_2 = j4.44 \phi_m z_2 10^{-8}$$

$$\hat{Z} = R + jX$$

$$Z = \sqrt{R^2 + (L\omega)^2}$$

$$\hat{M}_1 = \hat{E}_1 + \hat{I}_1 \hat{Z}_1 + j\omega L_{1R} \hat{I}_1$$

$$M_2 = \hat{E}_2 - \hat{I}_2 \hat{Z}_2 + j\omega L_{1R} \hat{I}_2$$

$$\hat{M}_1 = \hat{E}_1 + \hat{I}_1 (\hat{Z}_2 + j\omega L_{1R})$$

$$M_2 = \hat{E}_2 - \hat{I}_2 (\hat{Z}_2 - j\omega L_{1R})$$

\hat{E}_1

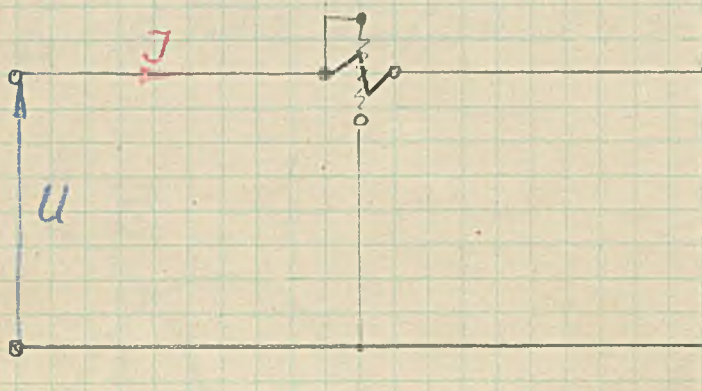
\hat{E}_2

dobry

Egzamin ustny z Podstaw elektr.

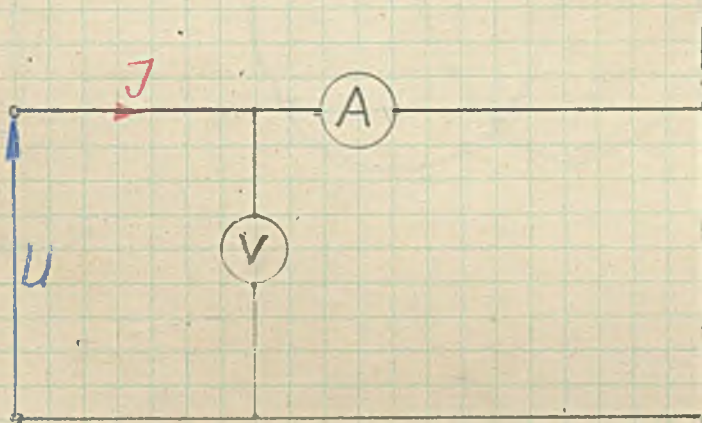
Pomiar mocy :

Pomiar mocy prądu stałego.



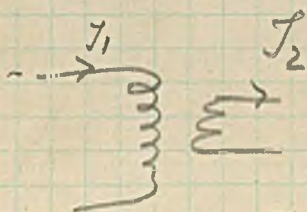
Przy pomocy watomierza

$$P = U \cdot I;$$



Przy pomocy
Woltomierza i Amperom.

$$P = UI;$$



$$I_2 = I_1 \frac{Z_1}{Z_2}$$

$$\phi = \phi_1 - \phi_2 = \frac{0,4\pi I_1 Z_1}{S} - \frac{0,4\pi I_2 Z_2}{S} =$$

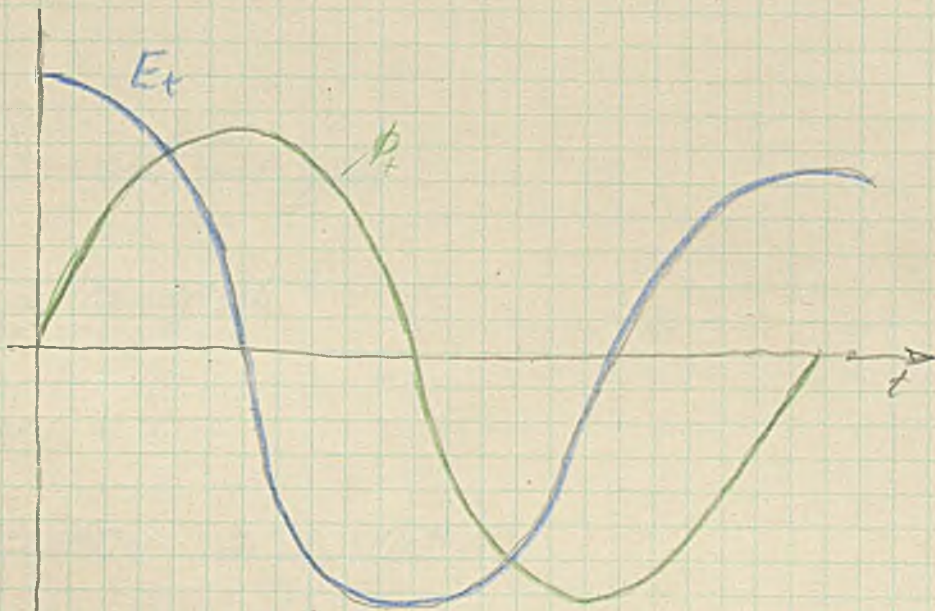
$$I_2 = I_1 \frac{Z_1}{Z_2}$$

$$E_t = L \frac{d\phi_t}{dt} 10^{-8} \text{ V}$$

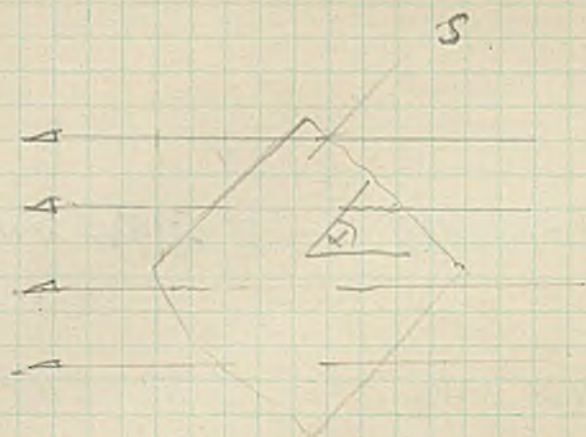
$$\phi_t = \phi_m \sin(\omega t + \alpha)$$

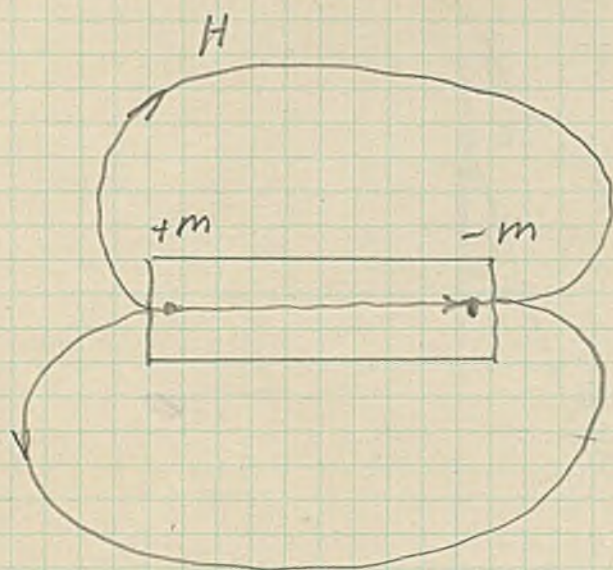
$$E_t = L \frac{d}{dt} \phi_m \sin(\omega t + \alpha) 10^{-8} = L \omega \phi_m \sin(\omega t + \alpha + \frac{\pi}{2}) 10^{-8}$$

$$E_t = 2\pi f L \phi_m (\omega t + \alpha + \frac{\pi}{2}) \quad \omega = 2\pi f$$



$$\Phi = \int_S \vec{B} \cdot d\vec{s} =$$





$$H = \frac{F}{m} = \sum \frac{m_i}{\mu l_i}$$

$$\text{dim} F = L M T^{-2}$$

$$\langle F \rangle = \text{cal fms} \text{ gcm}^{-2}$$

$$\langle F \rangle_{\text{CGS}} = \text{cm g sek}^{-2}$$

$$F = 100$$

$$F = 100 \text{ cm g sek}^{-2}$$

$$F = 100 \text{ dyn}$$

$$H = \frac{0.4 \pi I z}{l_{\text{cm}}} \quad A$$

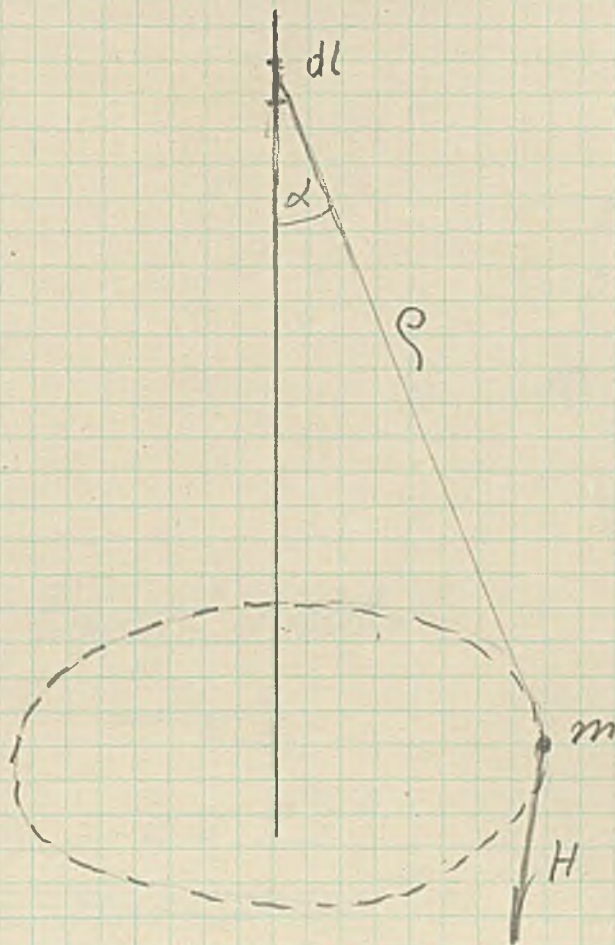
$$H_k = \frac{I A}{l_m}$$

$$n O'' = \frac{4 \pi}{10} O''$$

$$K = 30000 \text{ V/cm}$$

$$K_k = 3000000 \text{ V/cm}$$

Karłowicz Karol



$$dF = m \frac{J_{dl} \sin \alpha}{\rho^2} \text{ dyn}$$

$$dF = m \frac{J_A dl \sin \alpha}{10 \rho^2} \text{ dyn}$$

$$MA = 10A = 3 \cdot 10^9 EA$$

$$dF = \frac{m J_{EA} dl \sin \alpha}{3 \cdot 10^9 \rho^2}$$

$$dF = \frac{m J_{mA} dl \sin \alpha}{10 \cdot 10^3 \rho^2}$$

$$dF = \frac{m J_{kA} dl \sin \alpha \cdot 10^3}{10 \rho^2}$$

$$1A = 10^{-3} mA$$

$$1kA = 10^3 A$$

Kantoch Karol. $R_w = 18 \Omega$

$$Z = 20$$

J

μA

$$5 \cdot 10^{-6} A$$

$$50 mA$$

$$5 \cdot 10^{-2}$$

$$50 \mu A$$

$$J_x = 0,8 HL$$

$$5 \cdot 10^{-2} \cdot 20 = 0,8 HL$$

$$5 \cdot 10^{-6} \cdot X = 0,8 HL$$

$$\frac{20 \cdot 5 \cdot 10^{-6} X}{5 \cdot 10^{-2} \cdot 20} = 1$$

$$\frac{5 \cdot 10^{-4} X}{20 X} = 1$$

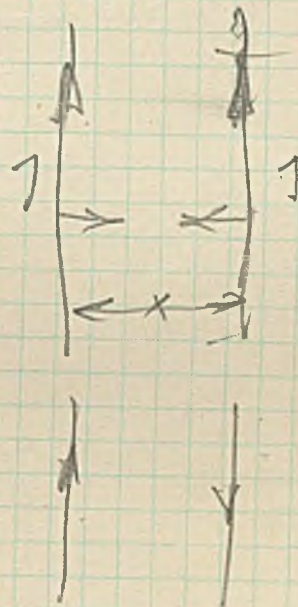
$$\frac{X}{20 \cdot 10^4} = 1$$

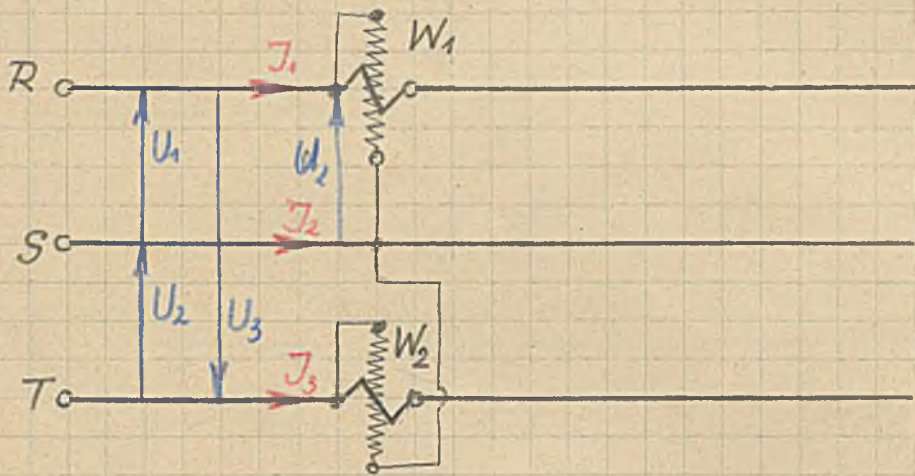
$$X = 20 \cdot 10^4 = 2 \cdot 10^5 \text{ zwój}$$

Łosci zwój / rebr
wicy.

$$\underline{\underline{\text{zwój} = 20 \cdot 10^4}}$$

$$\underline{\underline{F = \mu \cdot 2 \pi \cdot r_2 \cdot \frac{l}{x} \cdot dn}}$$



Pomiar mocy trójfazowej nierównomiernie obciążonego *obciążonego*

$$\hat{P}_1 = \hat{U}_1 \cdot \hat{J}_1$$

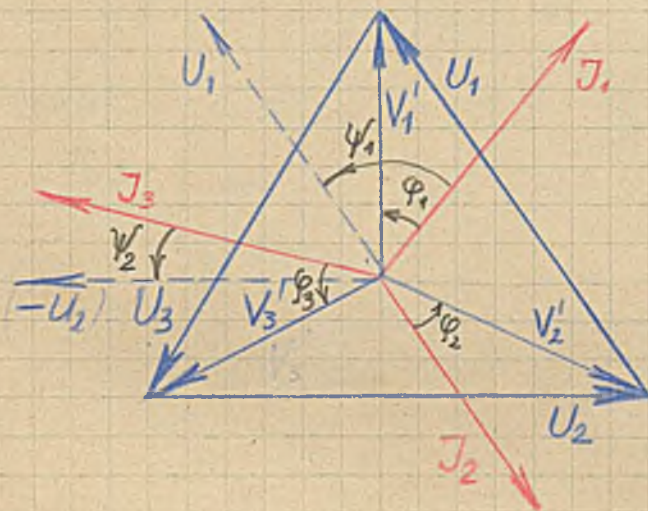
$$\hat{P}_2 = (-\hat{U}_2) \cdot \hat{J}_3$$

$$\hat{P} = \hat{P}_1 + \hat{P}_2 = \hat{U}_1 \cdot \hat{J}_1 + (-\hat{U}_2) \cdot \hat{J}_3 ;$$

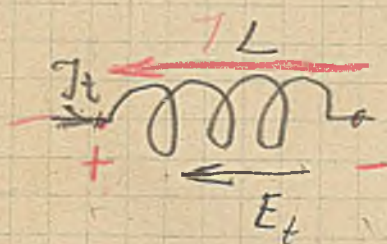
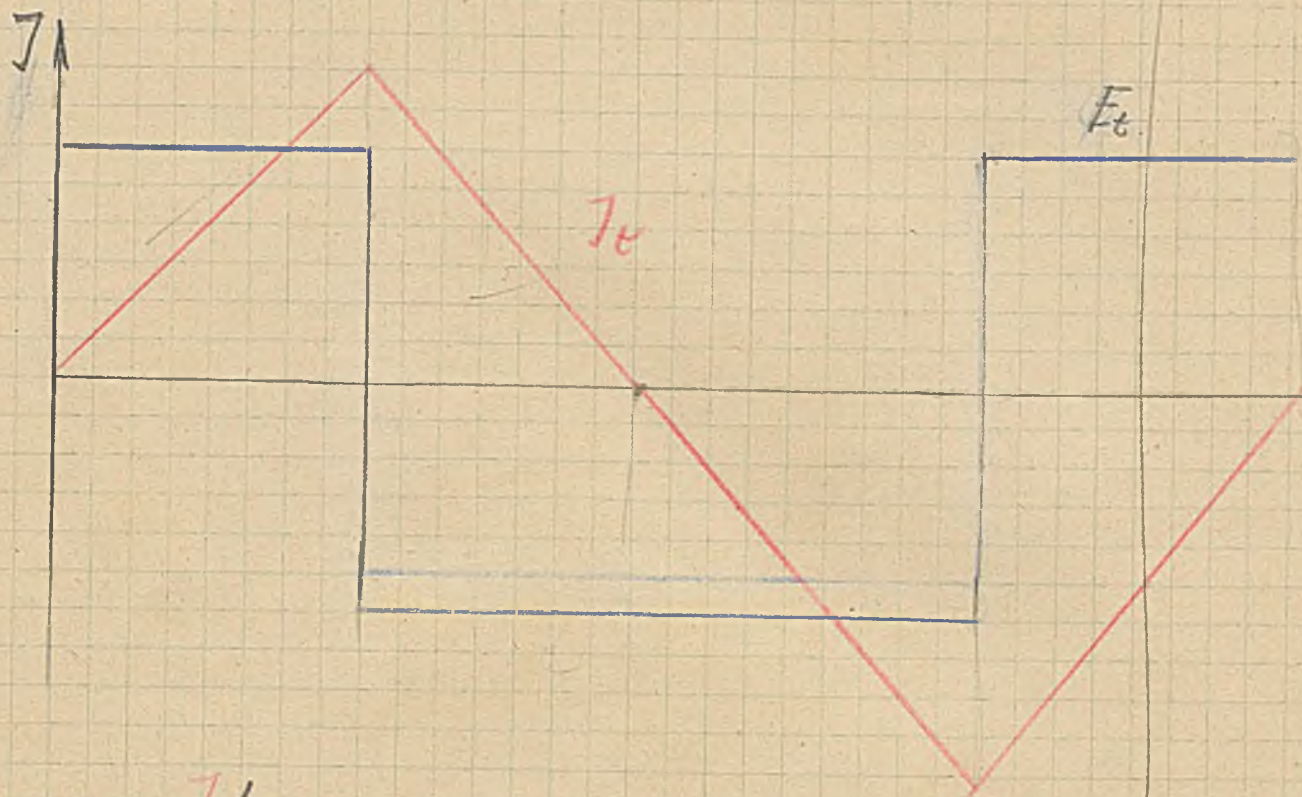
$$P_{1w} = U_1 \cdot J_1 \cdot \cos \psi_1 = U_1 J_1 \cos(\varphi_1 + 30^\circ)$$

$$P_{2w} = U_2 \cdot J_3 \cdot \cos \psi_2 = U_2 J_3 \cos(\varphi_3 - 30^\circ)$$

$$P = P_{1w} + P_{2w} = U_1 J_1 \cos(\varphi_1 + 30^\circ) + U_2 J_3 \cos(\varphi_3 - 30^\circ)$$



Kaňtoch Karol.

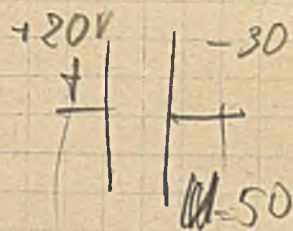


$$E_t = L \frac{dI_t}{dt}$$

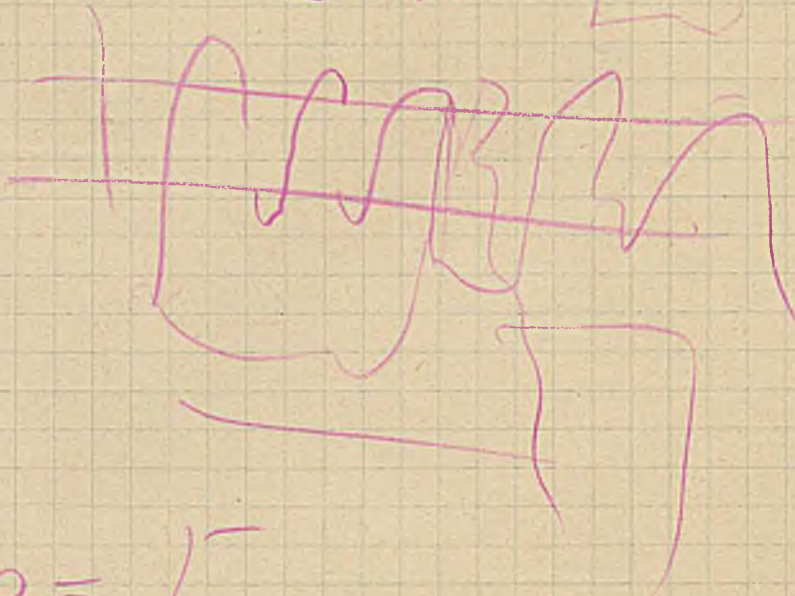
$$W = \frac{1}{2} L I^2$$

$$W = \frac{1}{2} C U^2$$

$$U = V_b - V_a$$



L R M

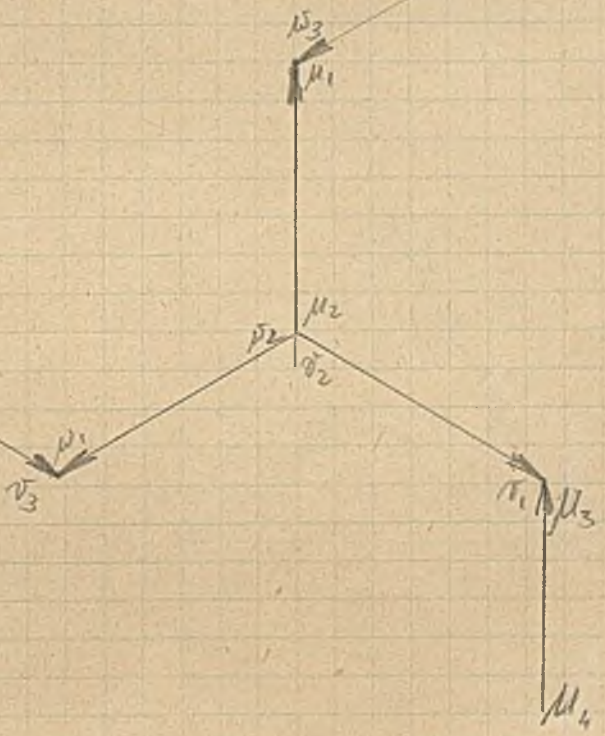
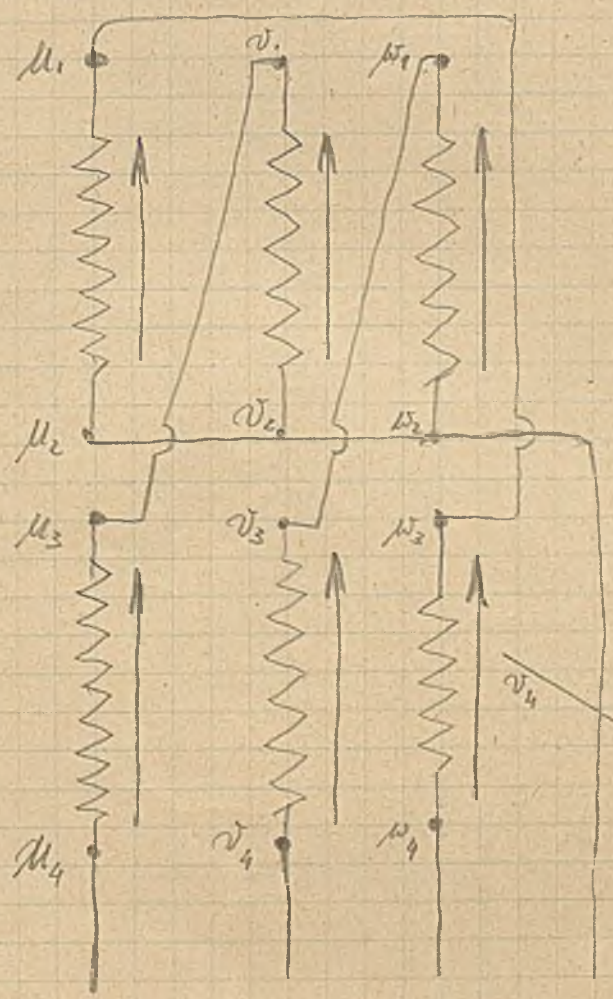
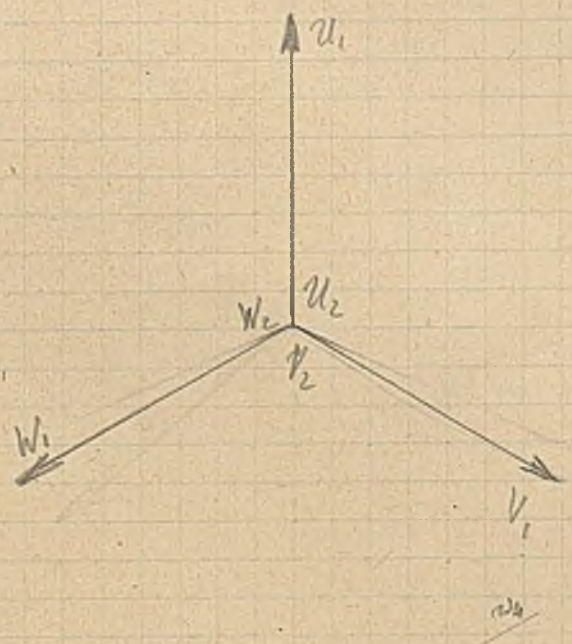
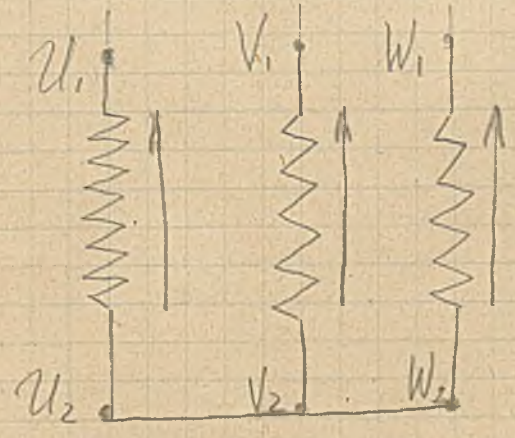


$$e = L \dot{i}$$

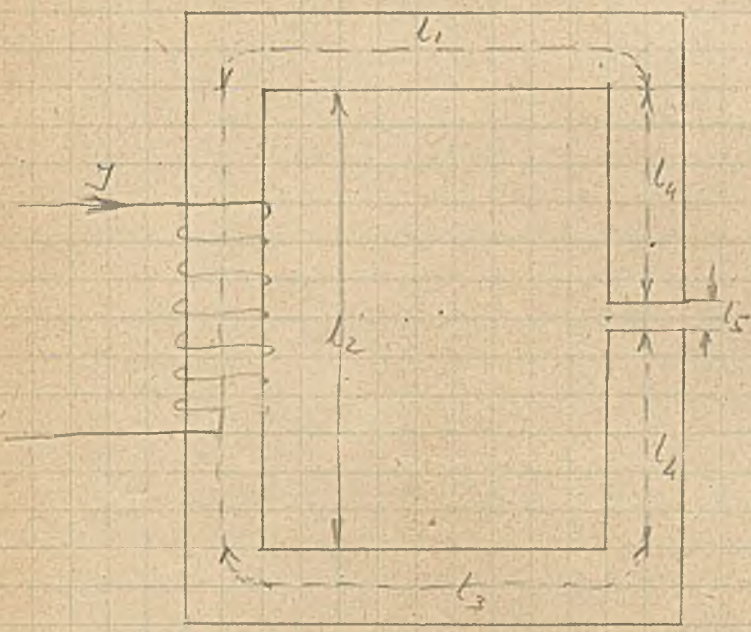
Bobusia Adolf

23. IX. 49

Examinacja ustna z
Podstaw Elektrotechniki



Magnetyczne prawo Ohma



$$\phi = \frac{N}{S}$$

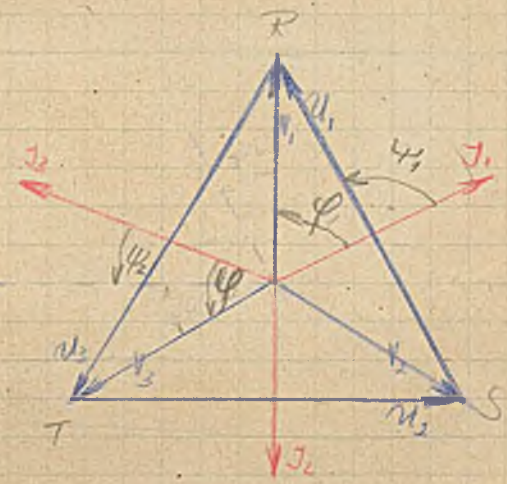
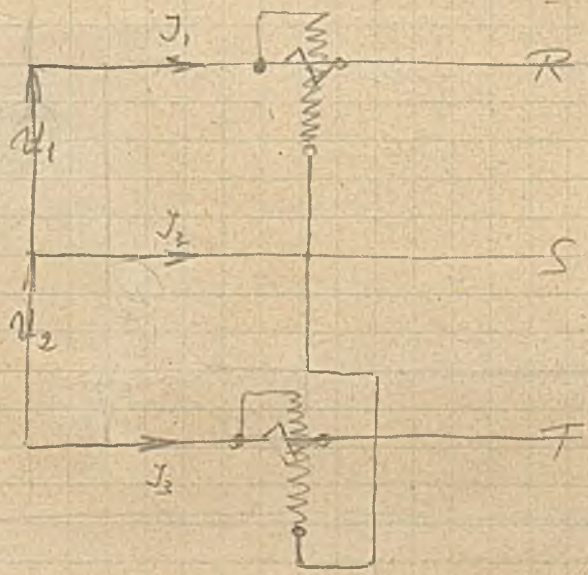
$$S = \frac{L}{\mu \rho}$$

$$\oint N = \oint (\phi S)$$

$$0.4 \pi J_m l = \oint \left(B \frac{l_i}{\mu} \right)$$

$$0.4 \pi J_m l = \oint (H l_i)$$

Pomiar mocy w układzie trójfazowym obciążonym równomiernie.



$$\psi_1 = \varphi + 30^\circ$$

$$\psi_2 = \varphi - 30^\circ$$

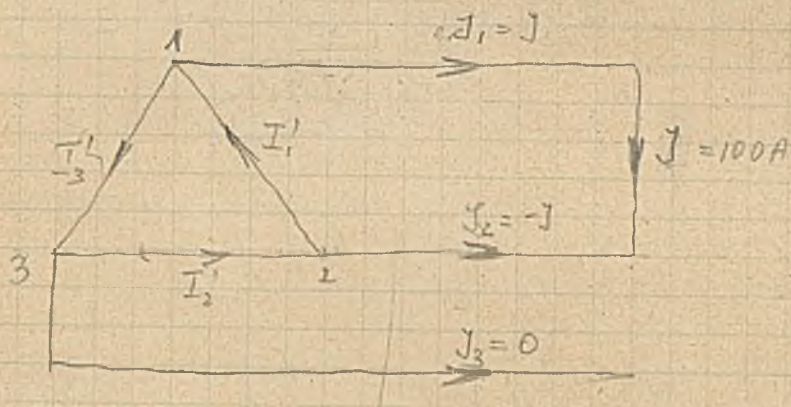
$$P_w = P_1 + P_2$$

$$P_1 = U_1 J_1 \cos \psi_1$$

$$P_2 = -U_2 J_3 \cos \psi_2$$

$$P_w = U_1 J_1 \cos \psi_1 - U_2 J_3 \cos \psi_2$$

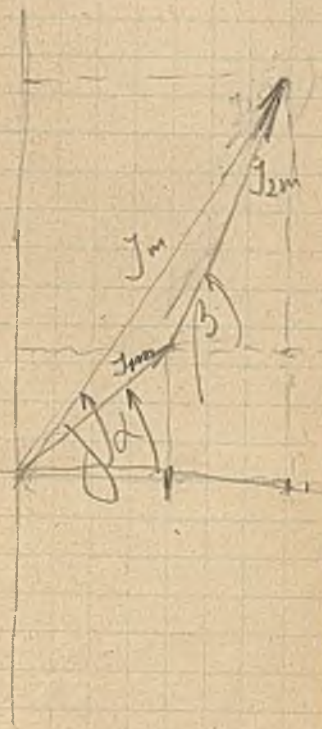
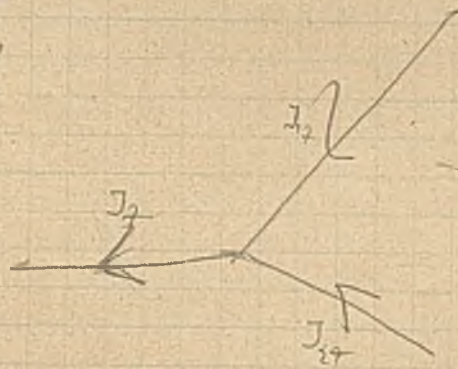
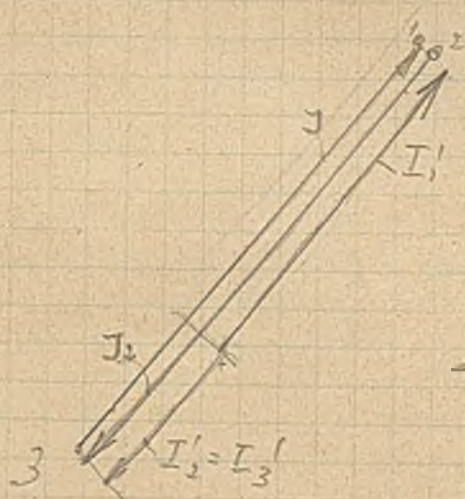
Dla równomiernego obciążenia $P = \sqrt{3} U J \cos \varphi$



$$\hat{I}_1' = \hat{J}_1 + \frac{1}{3}\hat{J}_2 + \frac{2}{3}\hat{J}_3 = \hat{J} - \frac{1}{3}\hat{J} = \frac{2}{3}\hat{J}$$

$$\hat{I}_2' = \hat{J}_2 + \frac{1}{3}\hat{J}_3 + \frac{2}{3}\hat{J}_1 = -\hat{J} + \frac{2}{3}\hat{J} = -\frac{1}{3}\hat{J}$$

$$\hat{I}_3' = \hat{J}_3 + \frac{1}{3}\hat{J}_1 + \frac{2}{3}\hat{J}_2 = \frac{1}{3}\hat{J} - \frac{2}{3}\hat{J} = -\frac{1}{3}\hat{J}$$



$$J_{1t} = J_{m1} \sin(\omega t + \alpha)$$

$$J_{2t} = J_{m2} \sin(\omega t + \beta)$$

$$J_{2m} = J_{m1} \sin(\omega t + \alpha) + J_{m2} \sin(\omega t + \beta) =$$

$$= J_{m1}(\sin \omega t \cos \alpha + \cos \omega t \sin \alpha) + J_{m2}(\sin \omega t \cos \beta + \cos \omega t \sin \beta)$$

$$= (J_{m1} \cos \alpha + J_{m2} \cos \beta) \sin \omega t + (J_{m1} \sin \alpha + J_{m2} \sin \beta) \cos \omega t =$$

$$= J_{m1} \cos \alpha \sin \omega t + J_{m2} \cos \beta \sin \omega t + J_{m1} \sin \alpha \cos \omega t + J_{m2} \sin \beta \cos \omega t = J_m \sin(\omega t + \gamma)$$

$$I_m = \left(I_{1m} \cos \alpha + I_{2m} \cos \beta \right)^2 + \left(I_{1m} \sin \alpha + I_{2m} \sin \beta \right)^2$$

$$\frac{I_1}{I_2} = \frac{I_{1m} \sin \alpha + I_{2m} \sin \beta}{I_{1m} \cos \alpha + I_{2m} \cos \beta}$$

$$\hat{I}_{1t} = \hat{I}_{1m} e^{j\omega t}$$

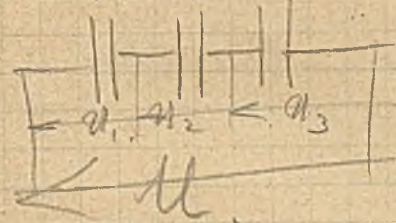
$$\hat{I}_{2t} = \hat{I}_{2m} e^{j\omega t}$$

$$\hat{I}_{1m} = I_m e^{j\alpha}$$

$$\hat{I}_{2m} = I_m e^{j\beta}$$

$$\hat{I}_2 = \hat{I}_{1t} + \hat{I}_{2t} = (\hat{I}_{1m} + \hat{I}_{2m}) e^{j\omega t} = \hat{I}_m e^{j\omega t} = I_m e^{j\alpha} e^{j\omega t}$$

$$\hat{I}_m = I_m$$



$$C_2 = 2C_1, \quad C_3 = 3C_1$$

$$u_1 + u_2 + u_3 = u$$

$$C_1 = \frac{Q}{u_1}$$

$$C_2 = \frac{Q}{u_2}$$

$$C_3 = \frac{Q}{u_3}$$

$$u_3 = \frac{Q}{3C_1}$$

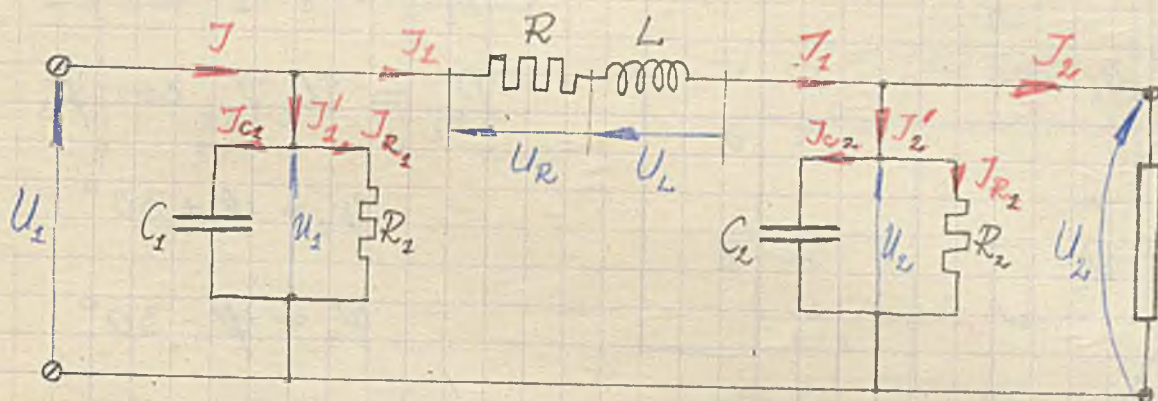
$$u_2 = \frac{Q}{2C_1}$$

Pracownia
sem V

17.12.49 r.

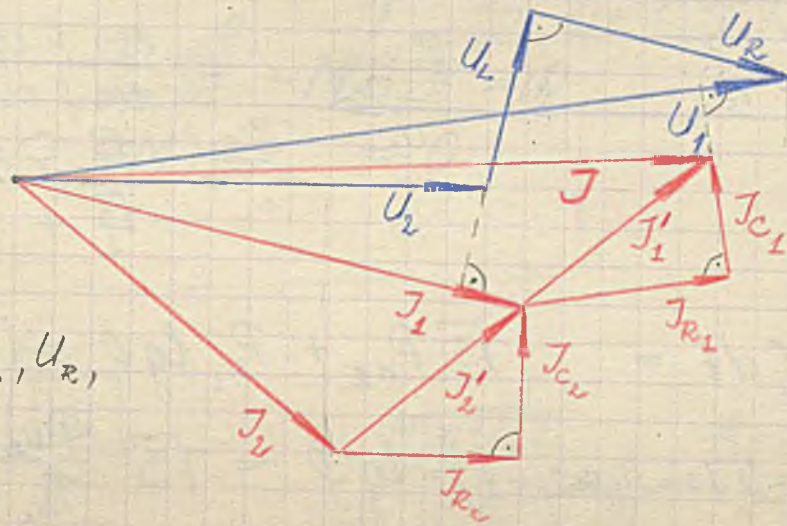
dobre

Examin ustny z Podstaw elektrotechniki



$$\hat{U}_2 = U_2 e^{j0^\circ} ; \quad \hat{J}_2 = J_2 e^{-j40^\circ}$$

Znaleźć U_1 i J metodą topograficznych wykresów napięć i prądów



Kolejność kreślenia:

$U_2, J_2, J_{R2}, J_{C2}, J_2', J_2'', U_L, U_R,$

$U_1, J_{R2}, J_{C2}, J_2', J_2''$

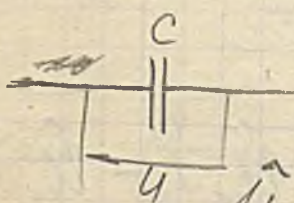
~~$A = CU$~~
 ~~$Q = CU$~~
 $Q = \frac{C}{\omega} \hat{J}$

~~$Q = C$~~

~~Jt~~

$W = \frac{1}{2} CU^2$

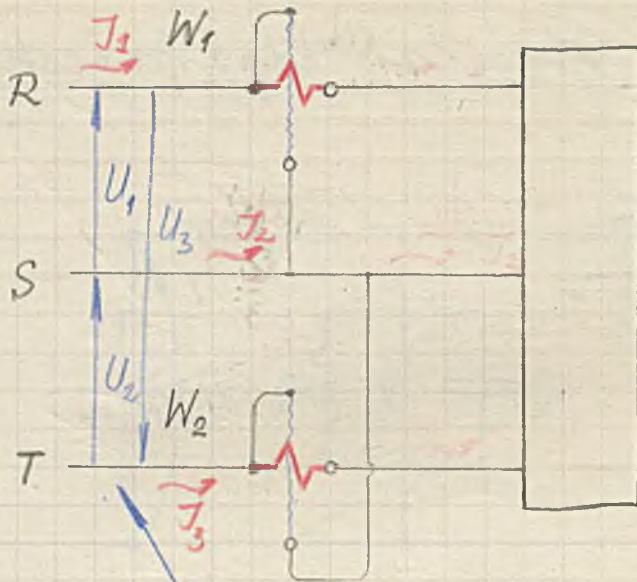
$W = \frac{1}{2} L J^2$



$\hat{U} = \frac{1}{C\omega} \hat{J}$

$J = \frac{1}{L} \int U dt$

Pomiar mocy w układzie Arona.



$$P_{\text{całk.}} = P_{W_1} + P_{W_2}$$

$$P_{W_1} = U_1 I_1 \cos \psi_1$$

$$P_{W_2} = U_2 I_3 \cos \psi_3$$

$$\psi_1 = \varphi + 30^\circ$$

$$\psi_3 = \varphi - 30^\circ$$

$$P_{\text{całk.}} = U_1 I_1 \cos(\varphi + 30^\circ) + U_2 I_3 \cos(\varphi - 30^\circ)$$

$$P_b = P \operatorname{tg} \varphi$$

$$\operatorname{tg} \varphi = \frac{P_{W_2}}{P_{W_1}} = \frac{\cos(\varphi + 30^\circ)}{\cos(\varphi - 30^\circ)} =$$

$$= \frac{\cos \varphi \cos 30^\circ - \sin \varphi \sin 30^\circ}{\cos \varphi \cos 30^\circ + \sin \varphi \sin 30^\circ} =$$

$$= \frac{\frac{\sqrt{3}}{2} - \frac{1}{2} \operatorname{tg} \varphi}{\frac{\sqrt{3}}{2} + \frac{1}{2} \operatorname{tg} \varphi} = \frac{\sqrt{3} - \operatorname{tg} \varphi}{\sqrt{3} + \operatorname{tg} \varphi}$$

$$Q = \frac{1}{T} \int_0^T u_i i_i dt = \sqrt{3} P_{W_1} + P_{W_2} \operatorname{tg} \varphi = \sqrt{3} P_{W_2} - P_{W_1} \operatorname{tg} \varphi$$

$$= U I \cos \varphi + U I \sin(\varphi + 2\varphi - \frac{\pi}{2}) \operatorname{tg} \varphi = \sqrt{3} \frac{P_{W_2} - P_{W_1}}{P_{W_1} + P_{W_2}} = \sqrt{3} \frac{P_{W_2} - P_{W_1}}{P}$$

$$= U I \operatorname{cosp} ;$$

$$P_b = \sqrt{3} (P_{W_2} - P_{W_1}) ;$$

$$P_p = \sqrt{P_n^2 + P_b^2} ;$$

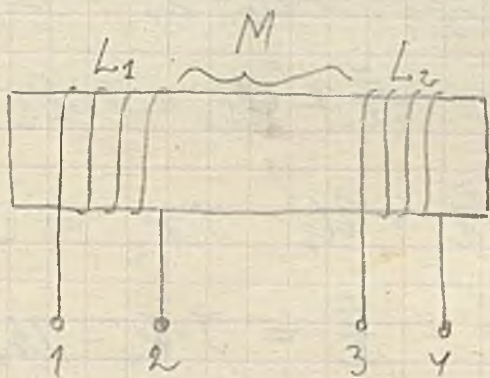
Symbolicznie:

$$\hat{P} = \hat{P}_1 + \hat{P}_2$$

$$\hat{P}_1 = \hat{U}_1 \hat{I}_1 ; \quad \hat{P}_2 = -\hat{U}_2 \hat{I}_3 ;$$

$$\hat{P} = \hat{U}_1 \hat{I}_1 - \hat{U}_2 \hat{I}_3$$

1)



I / 1-3, 2-4

$L = ?$

a) $M = \sqrt{L_1 L_2}$

b) $M = 0$

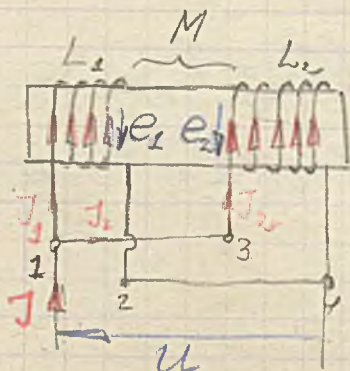
II 2-3

$L_2 = ?$

a) $M = \sqrt{L_1 L_2}$

b) $M = 0$

ad I



a) $M = \sqrt{L_1 L_2}$

b) $M = 0$

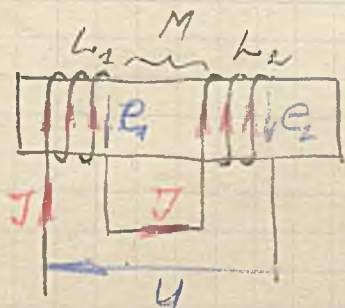
$$\hat{U} = L_1 \frac{d\hat{J}_1}{dt} + M \frac{d\hat{J}_2}{dt}$$

$$\hat{U} = L_2 \frac{d\hat{J}_2}{dt} + M \frac{d\hat{J}_1}{dt}$$

$$L_1 \frac{d\hat{J}_1}{dt} + M \frac{d\hat{J}_2}{dt} - L_2 \frac{d\hat{J}_2}{dt} - M \frac{d\hat{J}_1}{dt} = 0$$

$$(L_1 - M) \frac{d\hat{J}_1}{dt} - (L_2 - M) \frac{d\hat{J}_2}{dt} = 0$$

ad II



a) $M = \sqrt{L_1 L_2}$

b) $M = 0$

$$\hat{U} = \hat{E}_1 + \hat{E}_2$$

$$\hat{E}_1 = (L_1 + M) \frac{d\hat{J}}{dt}$$

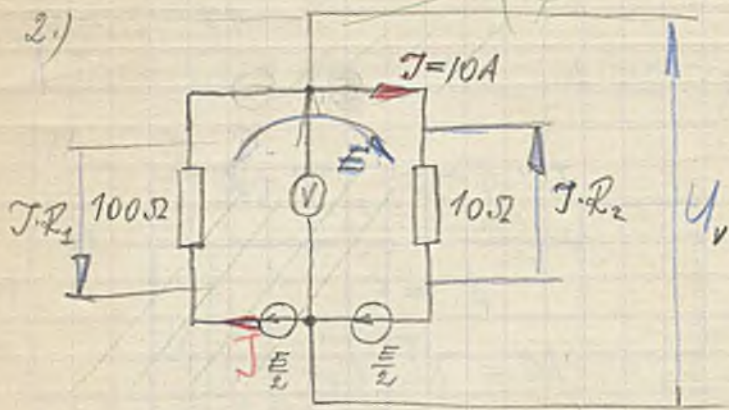
$$\hat{E}_2 = (L_2 + M) \frac{d\hat{J}}{dt}$$

$$\hat{U} = \underbrace{(L_1 + L_2 + 2M)}_L \frac{d\hat{J}}{dt}$$

a) dla $M = \sqrt{L_1 L_2}$, $L = L_1 + L_2 + 2\sqrt{L_1 L_2}$

b) dla $M = 0$, $L = L_1 + L_2$

2.)



$$\frac{E}{2} - J \cdot R_1 - U_V = 0$$

$$\frac{E}{2} = U_V + J \cdot R_1$$

$$\frac{E}{2} + U_V - J \cdot R_2 = 0$$

$$\frac{E}{2} = J \cdot R_2 - U_V$$

$$J \cdot R_2 - U_V = U_V + J \cdot R_1$$

$$2U_V = J(R_2 - R_1)$$

$$U_V = \frac{J}{2}(R_2 - R_1)$$

$$\underline{U_V} = 5(100 - 10) = \underline{\underline{450V}}$$

